

Networks - Fall 2005

Chapter 2

Play on networks 2: Strategic complements

Ballester, Calvó-Armengol and Zenou 2005

October 31, 2005

Summary



- Introduction  
- Nash equilibrium in pure strategies.  
- Example  
- Interpretation: Counting path length  
- Policy: The Key Player  
- Generalization of above set-up.  

- Let network g with $g_{ij} \in \{0, 1\}$.
- For all $i \in N$, action $x_i \geq 0$.
- $\frac{\partial^2 u_i}{\partial x_i \partial x_j} = g_{ij} b''(x_i + \bar{x}_i) \leq 0$ in Bramoullé-Kranton.
- $\frac{\partial^2 u_i}{\partial x_i \partial x_j} = g_{ij} \lambda \geq 0$ here. Local strategic complements.
- Linear-quadratic utilities

$$u_i(x_1, \dots, x_n; g) = \alpha x_i - \frac{1}{2} x_i^2 + \lambda \sum_{j \in N} g_{ij} x_i x_j; \lambda \geq 0, \alpha > 0.$$

- With $\lambda = 0$, no interdependence and $x_i^* = \alpha$.
- With $\lambda > 0$, interdependence.

- FOC:

$$\frac{\partial u_i}{\partial x_i} = \alpha - x_i + \lambda \sum_{j \in N} g_{ij} x_j = 0.$$

- FOC ($x_i - \lambda \sum_{j \in N} g_{ij} x_j = \alpha$) in general gives a system of equations

$$[I - \lambda G] \vec{x} = \alpha \vec{1}.$$

- Determinant of $[I - \lambda G]$ is a polynomial in λ , thus generically invertible matrix.

- We study this more in depth later.
- Now, suppose you have a regular network, where for all $i \in N$, $\sum_{j \in N} g_{ij} = k$.
- Then an equilibrium exists with $x_i = x$ for all $i \in N$. We must have $\alpha - x + \lambda kx = 0$, thus $x^* = \frac{\alpha}{1 - \lambda k}$ (assuming $\lambda k < 1$).
- For $\lambda > 0$, $x^*(\lambda)$ is increasing in λ (when equilibrium exists).
- In general, outcome will depend on the network, when there is heterogeneity.

Nash equilibrium in pure strategies. (1/5)



Remark 1 We show here there is a generically unique Nash equilibrium in pure strategies.

- Notice that $u_i(x_1, \dots, x_n; g)$ is such that $\frac{\partial^2 u_i}{\partial x_i^2} = -1 < 0$. This implies:

- x^* is a Nash equilibrium iff for all $i \in N$ either

1(a) $x_i^* = 0$ and $\frac{\partial u_i}{\partial x_i}(0, x_{-i}^*) \leq 0$

(b) $x_i^* > 0$ and $\frac{\partial u_i}{\partial x_i}(x^*) = 0$.

- But notice that if $x_i^* = 0$, $\frac{\partial u_i}{\partial x_i}(0, x_{-i}^*) = \alpha + \lambda \sum_{j \in N} g_{ij} x_j^* > 0$.

- Thus only (b) is relevant and x^* is a Nash equilibrium iff:

$$[I - \lambda G] \vec{x}^* = \alpha \vec{1}, \text{ and } x_i^* > 0 \text{ for all } i \in N.$$





- Solution of former equation exists and is unique iff $\det [I - \lambda G] \neq 0$.
- There exists a finite number of values of λ such that $[I - \lambda G]$ is degenerate, and it has Lebesgue measure zero, thus generically unique Nash equilibrium.
- When a solution exists, is it necessarily in \mathfrak{R}^+ ?
- Debreu and Herstein (1953), the matrix $[I - \lambda G]^{-1} = M(g, \lambda)$ is well-defined and non-negative iff λ is smaller than the largest eigenvalue of G .
- If λ is small enough

$$[I - \lambda G]^{-1} = \sum_{k \geq 0} \lambda^k G^k$$

Nash equilibrium in pure strategies. (3/5)



- To see this diagonalize $G = P^{-1} \begin{bmatrix} \mu_1 & \dots & 0 \\ \dots & \mu_i & \dots \\ 0 & \dots & \mu_n \end{bmatrix} P$.

- Thus $\lambda^k G^k = P^{-1} \begin{bmatrix} (\lambda\mu_1)^k & \dots & 0 \\ \dots & (\lambda\mu_i)^k & \dots \\ 0 & \dots & (\lambda\mu_n)^k \end{bmatrix} P$.

- So if $\lambda \max_i \{\mu_i\} < 1$, $\sum_{k \geq 0} \lambda^k G^k$ converges and

$$\vec{x}^* = \alpha [I - \lambda G]^{-1} \vec{1}$$

- Summarizing the above we have:

Proposition 2 *Let $\mu_1(g)$ be the largest positive eigenvalue of G . If $\lambda\mu_1(g) < 1$, the game has a unique interior pure strategy equilibrium given by*

$$\frac{x_i^*}{\alpha} = m_{i1}(g, \lambda) + \dots + m_{in}(g, \lambda)$$

with $M(g, \lambda) = [m_{ij}(g, \lambda)] = [I - \lambda G]^{-1} = \sum_{k \geq 0} \lambda^k G^k$.

Notice differences with previous model:

1. Equilibrium unique with complement - multiplicity with substitutes.
2. Equilibrium interior with complement - interior equilibria unstable with substitutes.

Example (1/3)



Suppose a 3 person network, with 1 connected to 2 and 3.

$$\bullet G = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \Rightarrow G^2 = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}, G^3 = \begin{bmatrix} 0 & 2 & 2 \\ 2 & 0 & 0 \\ 2 & 0 & 0 \end{bmatrix}$$

$$\bullet \text{By induction } G^{2p} = \begin{bmatrix} 2^p & 0 & 0 \\ 0 & 2^{p-1} & 2^{p-1} \\ 0 & 2^{p-1} & 2^{p-1} \end{bmatrix}, G^{2p+1} = \begin{bmatrix} 0 & 2^p & 2^p \\ 2^p & 0 & 0 \\ 2^p & 0 & 0 \end{bmatrix}$$

$$\bullet x_1^* = \sum_{p=0}^{\infty} [\lambda^{2p} 2^p + \lambda^{2p+1} 2^p + \lambda^{2p+1} 2^p] = \frac{1}{1-2\lambda^2} + \frac{2\lambda}{1-2\lambda^2} = \frac{1+2\lambda}{1-2\lambda^2}$$

$$\bullet x_2^* = x_3^* = \sum_{p=0}^{\infty} [\lambda^{2p+1} 2^p + \lambda^{2p} 2^{p-1} + \lambda^{2p} 2^{p-1}] = \frac{1+\lambda}{1-2\lambda^2}.$$



Example (2/3)



- Condition for existence $1 - 2\lambda^2 > 0$, $\lambda < 1/\sqrt{2}$.
- In general for a star with n nodes, largest eigenvalue of $G = \sqrt{n-1}$.

Interpretation: Counting path length (1/3)



- How many paths are there (in example) starting at node i between individuals i and j with length 2 (not repeating traveled through nodes)?
- Between 1&1 - 2, between 1&2 or 1&3 - 0.
- Between 2&1 - 0, between 2&2 or 2&3 -1.
- Between 3&1 - 0, between 3&2 or 3&3 -1.

- Notice that $G^2 = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix}$.

- This is general. For $G^k = [g_{ij}^{[k]}]$ counts total number of paths in g of length k starting at node i between individuals i and j .

Interpretation: Counting path length (2/3)



- Now $\sum_{k \geq 0} \lambda^k g_{ij}^{[k]}$ is the total number of paths in g of all lengths between individuals i and j but discounting paths of length k by λ^k .
- Remember $m_{ij}(g, \lambda) = \sum_{k \geq 0} \lambda^k g_{ij}^{[k]}$.

Definition 3 Bonacich (1987). Take network g and parameter λ small enough. The network centrality of individual i in g of parameter λ is

$$b_i(g, \lambda) \equiv \sum_{j=1}^n m_{ij}(g, \lambda) = \underbrace{m_{ii}(g, \lambda)}_{\text{self-loops}} + \underbrace{\sum_{j \neq i} m_{ij}(g, \lambda)}_{\text{outer-paths}}$$

- Since $\frac{x_i^*}{\alpha} = \sum_{j=1}^n m_{ij}(g, \lambda) = b_i(g, \lambda)$, the equilibrium action is proportional so Bonacich centrality.

In first place one must propose a planner's objective.

1. $F(g; \lambda, \alpha) = \sum_{j=1}^n x_j^* = \alpha \sum_{j=1}^n b_j(g, \lambda)$. This may be the measure if the network is simply a “factor of production” of a “good” or a “bad” (the model was originally created to study crime.)
2. $G(g; \lambda, \alpha) = \sum_{j=1}^n u_j(x^*; g)$. This is more useful if we think of a “public good” setup.

For the second measure notice that by FOC $\alpha - x_i^* + \lambda \sum_{j \in N} g_{ij} x_j^* = 0$.
Thus

$$u_j(x^*; g) = x_i^* \left(\alpha - \frac{1}{2} x_i^* + \lambda \sum_{j \in N} g_{ij} x_j^* \right) = x_i^* \left(0 + \frac{1}{2} x_i^* \right) = \frac{1}{2} x_i^{*2}$$

And thus

$$G(g; \lambda, \alpha) = \frac{1}{2} b_i(g, \lambda)^2.$$

PLANNER'S TOOLS-THE KEY PLAYER

- Classical public economics tools (tax subsidy) modify: λ, α .
- To the extent she can control it \rightarrow Modify g
 - Reshuffle network.
 - Eliminate link(s).

Definition 4 Node i is a Key Player iff

$$i \in \arg \max_{j \in N} \left\{ \sum_{k=1}^n b_k(g, \lambda) - \sum_{k \neq j} b_k(g^{-j}, \lambda) \right\}$$

- Notice that

$$\sum_{k=1}^n b_k(g, \lambda) - \sum_{k \neq j} b_k(g^{-j}, \lambda) = \underbrace{b_i(g)}_{i\text{'s direct contribution}} + \underbrace{\sum_{k \neq j} (b_k(g, \lambda) - b_k(g^{-j}, \lambda))}_{i\text{'s indirect contribution}}.$$

- Thus Key Player need not be the player with highest centrality, since indirect contribution also matters.

- Example:

Proposition 5 *Node i is a Key Player iff*

$$i \in \arg \max_{j \in N} \left\{ \frac{b_j(g, \lambda)^2}{m_{jj}(g)} \right\}$$

To show this we first prove:

Policy: The Key Player (4/7)



Lemma 6 $m_{ij}(g) \cdot m_{ik}(g) = \underbrace{m_{ii}(g) [m_{jk}(g) - m_{jk}(g^{-1})]}_B$

Proof. $m_{ii}(g) = \sum_{p \geq 0} \lambda^p g_{ii}^{[p]}$

$$m_{jk}(g) - m_{jk}(g^{-1}) = \sum_{\substack{p \geq 0 \\ p \geq 2 \text{ (at least need 2 steps)}}} \lambda^p \underbrace{\left[g_{jk}^{[p]} - g_{j(-i)k}^{[p]} \right]}_{\substack{g_{j(i)k}^{[p]} \\ \text{paths } jk \text{ through } i}}$$

Thus

$$B = \sum_{p=2}^{\infty} \lambda^p \left[\sum_{\substack{r+s=p \\ r \geq 0, s \geq 2}} g_{ii}^{[r]} \cdot g_{j(i)k}^{[s]} \right]$$

Policy: The Key Player (5/7)



Notice that $\left(\sum_{p \geq 1} \lambda^p x^p\right) \left(\sum_{p \geq 1} \lambda^p y^p\right) = \sum_{p \geq 2} \lambda^p \left(\sum_{r+s=p} x^r y^s\right)$

Thus

$$\sum_{p \geq 2} \lambda^p \sum_{r^i + s^i = p} g_{ji}^{[r^i]} \cdot g_{ik}^{[s^i]} = \left(\sum_{p \geq 1} \lambda^p g_{ji}^{[p]}\right) \left(\sum_{p \geq 1} \lambda^p g_{ji}^{[p]}\right)$$



Now to prove the proposition. By lemma:

$$\begin{aligned} \sum_{k \neq j} \left(b_k(g, \lambda) - b_k(g^{-j}, \lambda)\right) &= \sum_{j \neq i} \sum_k \left[m_{jk}(g) - m_{jk}(g^{-1})\right] \\ &= \sum_{j \neq i} \sum_k \frac{m_{ij}(g) \cdot m_{ik}(g)}{m_{ii}(g)} \\ &= \sum_{j \neq i} \frac{m_{ij}(g)}{m_{ii}(g)} \underbrace{\sum_k m_{ik}(g)}_{b_i(g, \lambda)} \end{aligned}$$

Thus:

$$\begin{aligned} b_i(g) + \sum_{k \neq j} (b_k(g, \lambda) - b_k(g^{-j}, \lambda)) &= b_i(g) \left[1 + \sum_{j \neq i} \frac{m_{ij}(g)}{m_{ii}(g)} \right] \\ &= b_i(g) \left[\frac{m_{ii}(g) + \sum_{j \neq i} m_{ij}(g)}{m_{ii}(g)} \right] \\ &= \frac{b_i(g)^2}{m_{ii}(g)} \end{aligned}$$

- Note that $\frac{b_i(g)^2}{m_{ii}(g)} = b_i(g) \left[1 + \sum_{j \neq i} \frac{m_{ij}(g)}{m_{ii}(g)} \right]$,
- Thus what matters is not only centrality, but also the composition of the contribution.
- If the relative weight of outer paths to self loops is larger, more likely to be Key Player.

Generalization of above set-up.



Let

$$u_i(x_1, \dots, x_n; g) = \alpha x_i + \sum_{j \in N} \sigma_{ij} x_i x_j; \lambda \geq 0, \alpha > 0.$$

$$\underline{\sigma} = \min_{ij \in g} \sigma_{ij}; \bar{\sigma} = \max_{ij \in g} \sigma_{ij}; \frac{\partial^2 u_i}{\partial x_i^2} = \sigma_{ii} < 0$$

Conditions: $\sigma_{ii} = \sigma < \min\{0, \underline{\sigma}\}$, concavity on myself is highest.

In Bramoullé-Kranton: $\frac{\partial^2 u_i}{\partial x_i^2} = b''(x_i + \bar{x}_i) = \frac{\partial^2 u_i}{\partial x_i \partial x_j}$; if $g_{ij} \neq 0$.

Networks - Fall 2005

Chapter 2

Play on networks 2: Strategic complements

Ballester, Calvó-Armengol and Zenou 2005

October 31, 2005