CONDITIONAL STOCHASTIC DOMINANCE TESTING

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Abstract

This article proposes bootstrap-based stochastic dominance tests for non-parametric conditional distributions and their moments. We exploit the fact that a conditional distribution dominates the other if and only if the difference between the marginal joint distributions is monotonic in the explanatory variable at each value of the dependent variable. The proposed test statistic compares restricted and unrestricted estimators of the difference between the joint distributions, and it can be implemented under minimal smoothness requirements on the underlying nonparametric curves and without resorting to smooth estimation. The finite sample properties of the proposed test is examined by means of a Monte Carlo study. We report an application to studying the impact on post-intervention earnings of the National Supported Work Demonstration, a randomized labor training program carried out in the 1970s.

Keywords and Phrases: Nonparametric testing; Conditional stochastic dominance; Conditional inequality restrictions; Least concave majorant; Treatment effects.
1. INTRODUCTION

Stochastic dominance plays a major role in applied research, particularly in economics. It has been used to rank investment strategies, to measure income and poverty inequality, or to assess treatments effects, social programs or policies. The earliest proposal of Smirnov (1939) in the classical two-sample problem has been followed by numerous extensions to different concepts of stochastic dominance under alternative data generating processes assumptions; see e.g. McFadden (1989), Anderson (1996), Davidson and Duclos (2000), Barrett and Donald (2003), Linton, Maasoumi and Whang (2005), or Scaillet and Topaloglou (2010), among others. This literature has been confined, however, to unconditional stochastic dominance testing, and although there are some proposals that can accommodate covariate heterogeneity, these tests are only consistent under rather strong independence assumptions between regression errors and covariates. This article proposes consistent tests for conditional stochastic dominance and other conditional moment inequalities under mild regularity conditions on the underlying data generating process and without requiring smoothed estimates.

Related to testing conditional stochastic dominance is the large literature on two-sided tests for the equality of nonparametric regression curves. Some of these tests compare smooth estimators of the nonparametric curves, like Härdle and Marron (1990), Hall and Hart (1990) or King, Hart and Wehrly (1991). Others avoid smooth estimation of conditional moments by comparing estimates of their integrals, like Delgado (1993) or Ferreira and Stute (2004). The literature on one-sided tests of conditional moment restrictions is by contrast rather scarce, and more recent. Tests for non-positiveness of conditional moments can be based on the positive part of a smoothed estimator, as it has been suggested by Hall and Yatchew (2005), or Lee and Whang (2009). A related idea has been implemented by Linton, Song and Whang (2011), who use the positive part of the difference between sample distributions in order to test stochastic dominance. One can avoid using smoothers by noticing that a conditional moment is non-positive if and only if its integral is monotonically non-
increasing. This fact has been exploited by Kim (2008) and Andrews and Shi (2010) for constructing confidence intervals of parameters partially identified by means of conditional moment inequalities. See also Khan and Tamer (2009) for an application to censored regression. So, as Andrews and Shi (2010) suggest, a test of monotonicity on the integrated curve can be used for testing the inequality restrictions.

Our approach is also based on integrated moments but relies on a different methodology to that of the aforementioned works. We first characterize the problem of testing for monotonicity of the integrated moment as one of testing for concavity, by integrating one more time. Then, instead of a Wald-type test statistic, as in Kim (2008) or Andrews and Shi (2010), we consider a Likelihood Ratio (LR)-type approach, comparing restricted and unrestricted estimates of the double-integrated conditional moment. Our approach is then more related to classical LR tests for parameter inequality restrictions. See Dykstra and Robertson (1982, 1983), Robertson, Wright and Dykstra (1988), Wolak (1989) or Kodde and Palm (1986). However, unlike in this classical literature, our null hypothesis is nonparametric, i.e. involves infinite restrictions. The restricted estimator of the integrated conditional moment is in fact an isotonic estimator, which does not use smoothers. See Barlow et al. (1972) for a comprehensive account of results on isotonic estimation, and see Durot (2003) and Delgado and Escanciano (2010) for applications of the isotonic regression principles to conditional moment monotonicity testing. The proposed conditional stochastic dominance test is easy to implement using available algorithms for nonparametric isotonic estimation. Also, it can be implemented under fairly weak assumptions on the underlying data generating process, and it is fully data-driven, without requiring user-chosen parameters such as bandwidths.

In this article, we focus on the first-order conditional stochastic dominance testing problem in a one-sample setting. Under the null, the difference between the two conditional distributions, or their moments, is non-positive/non-negative. The null hypothesis is satisfied if and only if the difference between the corresponding unconditional joint distribution functions is monotonic with respect to the explanatory variable. Thus, our tests consist of comparing restricted and unrestricted estimates
of the difference between the joint distribution functions. The limiting distribution of
the test statistic is non-pivotal in the least favorable case (l.f.c), i.e. the case under
the null closest to the alternative, but critical values can be consistently estimated
with the assistance of a bootstrap procedure as shown below.

The test statistic designed for testing conditional stochastic dominance is easily
adapted to testing inequality restrictions on other conditional moments, possibly in-
dexed by unknown parameters which must be estimated. Likewise, higher-order sto-
chastic dominance can be easily accommodated. Our testing procedure is particularly
well suited for the evaluation of treatment programs. We apply the testing method
to the National Supported Work (NSW) Demonstration program, a randomized labor
training program carried out in the 1970s, which has been employed for illustrating
different proposals for treatment effect evaluation ever since the landmark article by
Lalonde (1986). In this application we find evidence against a non-negative average
treatment effect conditional on age when the whole age distribution is included, and
we show that this rejection is mainly due to young individuals between 17 and 21
years old. For these young individuals the job training program was not beneficial.
Unconditional methods are unable to uncover this age heterogeneity in treatment ef-
fects. This feature of the data is also missed by methods using smoothers, because of
their lack of precision in the tails of the age distribution, where there are few observa-
tions. Hence, this application highlights the merits of the proposed methodology– the
conditional aspect and the gains in precision derived from estimating integrals rather
than derivatives.

We have organized the article as follows. In the next section, we present the testing
procedure. Section 3 is devoted to applications of the basic framework to situations
of particular practical relevance. We consider testing inequality restrictions on condi-
tional moments, possibly indexed by unknown parameters, which is illustrated with
an application to testing conditional treatment effects in social programs. We also
discuss the application of the testing procedure when conditioning on a vector of co-
variates. A Monte Carlo study in Section 4 investigates the finite sample properties
of the proposal. We also report in this section the application to the NSW study.
In Section 5 we conclude and suggest extensions for future research. Mathematical proofs are gathered in an Appendix at the end of the article.

2. CONDITIONAL STOCHASTIC DOMINANCE TESTING

Henceforth, all the random variables are defined on a probability space \((\Omega, \mathcal{A}, \mathbb{P})\).

Any generic random vector \(\mathbf{X}\) takes values in \(\mathcal{X}\), \(\mathcal{F}\) denotes its cumulative distribution function (cdf), and for each pair of random vectors \((\mathbf{X}_1, \mathbf{X}_2)\) on \((\Omega, \mathcal{A}, \mathbb{P})\), \(F_{\mathbf{X}_1 \mid \mathbf{X}_2}\) denotes the conditional cdf of \(\mathbf{X}_1\) given \(\mathbf{X}_2\), i.e.,

\[
F_{(\mathbf{X}_1, \mathbf{X}_2)}(t_1, t_2) = \int_{-\infty}^{t_2} F_{\mathbf{X}_1 \mid \mathbf{X}_2}(t_1, \tilde{t}_2) \, F_{\mathbf{X}_2}(d\tilde{t}_2).
\]

Given an \(\mathbb{R}^3\) valued random vector \((Y_1, Y_2, X)\) and sets \(\mathcal{W}_Y \subseteq \mathcal{X}_Y \cap \mathcal{X}_Y\) and \(\mathcal{W}_X \subseteq \mathcal{X}\), such that \(\mathcal{W}_Y \times \mathcal{W}_Y \times \mathcal{W}_X \subseteq \mathcal{X}(Y_1, Y_2, X)\), we consider the hypothesis

\[
H_0 : F_{Y_1 \mid X} \leq F_{Y_2 \mid X} \text{ a.s. in the set } \mathcal{W}_Y \times \mathcal{W}_X.
\]  

(1)

The alternative hypothesis \(H_1\) is the negation of \(H_0\). We allow, but do not require, that \(\mathcal{W}_Y \times \mathcal{W}_Y \times \mathcal{W}_X \equiv \mathcal{X}(Y_1, Y_2, X)\). The discussion is centered on the case where \(X\) is univariate and \(F_X\) is continuous. When \(X\) is discrete, the conditional distribution can be estimated \(\sqrt{n}\)-consistently, and \(H_0\) can be tested using simple modifications of existing unconditional methods. In Section 4, we consider the implementation when \(X\) is multivariate, where some of the components, but not all, can be discrete.

Note that \(H_0\) is satisfied if and only if the difference between the joint distributions,

\[
D(y, x) \equiv (F_{Y_1 \mid X}(y, x) - F_{Y_2 \mid X}(y, x))
= \int_{-\infty}^{x} (F_{Y_1 \mid X} - F_{Y_2 \mid X}) (y, \tilde{x}) \, F_X (d\tilde{x}),
\]

is non-increasing in \(x \in \mathcal{W}_X\), for each \(y \in \mathcal{W}_Y\). In turn, since the quantile function \(F_X^{-1}\) is non-decreasing, a necessary and sufficient condition for (1) is that

\[
C(y, u) \equiv \int_{0}^{u} D(y, F_X^{-1}(\tilde{u})) \, d\tilde{u}
\]

is concave in \(u \in \mathcal{U}_X \equiv F_X(\mathcal{W}_X)\), for each \(y \in \mathcal{W}_Y\). That is, the null hypothesis is satisfied if and only if the integrated curve \(D\) is monotonically non-increasing in
$x \in \mathcal{W}_X$, for each $y \in \mathcal{W}_Y$. Then, the monotonicity of $D$ is satisfied if and only if its integrated curve, $C$, is concave with respect to its second argument.

Therefore, $H_0$ can be characterized by the least concave majorant (l.c.m.) operator $\mathcal{T}$, which is defined as follows in this bivariate context. Let $\mathcal{C}$ be the space of concave functions on $[0, 1]$. For any generic measurable function $g : \mathcal{W}_Y \times \mathcal{U}_X \to \mathbb{R}$, $\mathcal{T} g (y, \cdot)$ is the function satisfying the following two properties for each $y \in \mathcal{W}_Y$: (i) $\mathcal{T} g (y, \cdot) \in \mathcal{C}$ and (ii) if there exists $h \in \mathcal{C}$ with $h \geq g (y, \cdot)$, then $h \geq \mathcal{T} g (y, \cdot)$. Henceforth, $\mathcal{T} g$ denotes the function resulting from applying the operator $\mathcal{T}$ to the function $g (y, \cdot)$ for each $y \in \mathcal{W}_Y$. Obviously, for a concave function $g$ on $[0, 1]$, $\mathcal{T} g = g$. Thus, $H_0$ can be rewritten as an equality restriction,

$$H_0 : \mathcal{T} C = C = 0, \text{ a.s. in the set } \mathcal{W}_Y \times \mathcal{U}_X.$$  

This suggests, using as test statistic, some functional of an estimator of $\mathcal{T} C - C$. Let $Z_n \equiv \{(Y_{1i}, Y_{2i}, X_i)\}_{i=1}^n$ be independent and identically distributed (iid) observations of $Z \equiv (Y_1, Y_2, X)$. Henceforth, for a given generic sample $\{\xi_i\}_{i=1}^n$ of a possibly multivariate random variable $\xi$, let $F_{\xi_n}$ denote its corresponding empirical cdf and $F_{\xi_n}^{-1}$ its corresponding empirical quantile. A natural estimator of $C$ is

$$C_n (y, u) \equiv \int_0^u D_n (y, F_{X_n}^{-1} (\tilde{u})) \, d\tilde{u}, \quad (y, u) \in \mathcal{W}_Y \times \mathcal{U}_X,$$

where

$$D_n (y, x) \equiv (F_{(Y_1, X)_n} - F_{(Y_2, X)_n}) (y, x), \quad (y, x) \in \mathcal{W}_Y \times \mathcal{W}_X.$$

Notice that $D_n \left( F_{Y_n}^{-1} (v), F_{X_n}^{-1} (u) \right), (v, u) \in [0, 1]^2$, is the sample analog of the difference between the copula functions of $(Y_1, X)$ and $(Y_2, X)$, $D \left( F_{Y}^{-1} (v), F_{X}^{-1} (u) \right)$, which has been considered by Remillard and Scaillet (2009) and Bücher and Dette (2010) for copula equality testing.

The test statistic is the sup-distance between $\mathcal{T} C_n$ and $C_n$, i.e.

$$\eta_n \equiv \sqrt{n} \sup_{(y, u) \in \mathcal{W}_Y \times \mathcal{U}_X} (\mathcal{T} C_n - C_n) (y, u),$$

where $\mathcal{U}_X \equiv F_{X_n} (\mathcal{W}_X)$ is the sample analog of $\mathcal{U}_X$. Of course, other distances could
be used. Notice that
\[ \hat{\eta}_n = \sqrt{n} \sup_{(y,u) \in \mathcal{W}_Y \times \mathcal{U}_{X_n}} \int_0^u (D_n^0 - D_n) (y, F_{X_n}^{-1} (u)) \, d\bar{u}, \]
where \( D_n^0 (y, F_{X_n}^{-1} (u)) \) is the slope of \( TC_n (y, u) \) for \( y \) fixed. Thus, \( \hat{\eta}_n \) is in fact a distance between a restricted and an unrestricted estimator of the difference between the joint distribution functions.

2.1. Computation of the test statistic

Note that, for \( (y, u) \in \mathcal{W}_Y \times \mathcal{U}_{X_n} \),
\[ C_n (y, u) = \frac{1}{n} \sum_{i=1}^n (1_{\{y_1 \leq y\}} - 1_{\{y_2 \leq y\}}) (u - F_{X_n} (X_i)) 1_{\{F_{X_n} (X_i) \leq u\}}. \tag{3} \]
Therefore, it is evident from (3) that \( C_n (y, \cdot) \) is, for each \( y \in \mathcal{W}_Y \), piecewise linear with knots in \( \mathcal{U}_{X_n} \), as is \( TC_n (y, \cdot) \). For each \( y \in \mathcal{W}_Y \), we can always write,
\[ C_n \left( y, \frac{l}{n} \right) = \frac{1}{n} \sum_{j=1}^l r_{nj} (y), \quad l = 1, \ldots, n, \]
for a suitable sequence \( \{r_{nj} (y)\}_{j=1}^n \) of first differences of \( C_n (y, \cdot) \), with \( r_{n1} (y) \equiv 0 \). In particular, when there are no ties in \( \{X_i\}_{i=1}^n \), the function \( r_{nj} (y) \) is given by,
\[ r_{nj} (y) \equiv \frac{1}{n} \sum_{i=1}^{j-1} \left( 1_{\{Y_{i[1:n]} \leq y\}} - 1_{\{Y_{2[1:n]} \leq y\}} \right), \quad j = 2, \ldots, n. \tag{4} \]
where \( \{Y_{j[i:n]}\}_{i=1}^n ; \ j = 1, 2 \), are the \( Y_j \)-concomitants of the order statistics \( \{X_{i[n]}\}_{i=1}^n \); i.e. \( Y_{j[i:n]} = Y_{jk} \) if \( X_{i:n} = X_k, \ j = 1, 2 \), with \( X_{1:n} < X_{2:n} < \cdots < X_{n:n} \).

The knots of \( TC_n (y, \cdot) \), for each \( y \in \mathcal{W}_Y \), are easily located applying the Pooled Adjacent Violators Algorithm (PAVA) proposed by Barlow et al. (1972). The input for the algorithm must be \( \{r_{ni} (y)\}_{i=1}^n \), which can be easily computed recursively according to (4) when there are no \( X \) ties, or simply by computing the increments of \( C_n (y, \cdot) \) in the general case. See Cran (1980) and Bril et al. (1982) for FORTRAN implementations and de Leeuw et al. (2009) for R routines. Moreover, the maximum difference of \( (TC_n - C_n) (y, \cdot) \), with \( y \in \mathcal{W}_Y \) fixed, is attained at one of the points in \( \mathcal{U}_{X_n} \), restricting the supremum to a maximum on a finite number of points for each
1. Furthermore, \( C_n(y, \cdot) \), and hence \( TC_n(y, \cdot) \), takes on the same values when \( y \) is between consecutive order statistics of the pooled sample \( \{Y_{1i}, Y_{2i}\}_{i=1}^n \), which shows that \( \sup_{y \in \mathcal{W}_Y} \) can be also computed as a maximum. Hence, we can simply write

\[
\eta_n = \sqrt{n} \max_{(y,u) \in (\mathcal{U}_{Y_n}, \mathcal{U}_{X_n})} (TC_n - C_n)(y,u), \tag{5}
\]

where \( \mathcal{U}_{Y_n} \equiv \{Y_{ki} : Y_{ki} \in \mathcal{W}_Y, 1 \leq i \leq n, k = 1,2 \} \). Matlab subroutines for computing \( \eta_n \) are available from the authors upon request.

2.2. Asymptotic distribution

We discuss now the asymptotic distribution of \( \eta_n \) under the least favorable case, which corresponds to (1) under equality. The limiting distribution follows from the functional central limit theorem applied to \( \sqrt{n}C_n \), and the continuous mapping theorem. But it must be proved first that considering the empirical distribution function \( F_{X_n} \) in \( C_n \) and in the estimated set \( \mathcal{U}_{X_n} \), rather than the genuine \( F_X \), does not have any effect on the asymptotic distribution of the test statistic under the l.f.c. In the Appendix we characterize the limiting distribution of \( \eta_n \) and prove that, under \( H_0 \),

\[
\lim_{n \to \infty} \mathbb{P}\{\eta_n > c_\alpha\} \leq \alpha,
\]

where

\[
c_\alpha = \inf \left\{ c \in [0, \infty) : \lim_{n \to \infty} \mathbb{P}\{\eta_n > c\} \leq \alpha \text{ in the l.f.c.} \right\}.
\]

However, \( c_\alpha \) is hard to estimate directly from the sample. We propose estimating \( c_\alpha \) by means of a multiplier-type bootstrap. See Chapter 2.9 in van der Vaart and Wellner (1996). The asymptotic critical value \( c_\alpha \) is estimated by

\[
c_{\alpha n}^* = \inf \left\{ c \in [0, \infty) : \mathbb{P}_n^* (\eta_n^* > c) \leq \alpha \right\},
\]

where \( \mathbb{P}_n^* \) means bootstrap probability, i.e. conditional on the sample \( \mathcal{Z}_n \),

\[
\eta_n^* \equiv \sqrt{n} \max_{(y,u) \in (\mathcal{U}_{n}, \mathcal{U}_{X_n})} (TC_n^* - C_n^*)(y,u)
\]

and, for each \( (y,u) \in \mathcal{W}_Y \times \mathcal{U}_{X_n} \),

\[
C_n^*(y,u) \equiv \frac{1}{n} \sum_{i=1}^n \left( 1\{Y_{1i} \leq y\} - 1\{Y_{2i} \leq y\} \right) (u - F_{X_n}(X_i)) \mathbb{1}_{\{F_{X_n}(X_i) \leq u\}} V_i.
\]
The random variables $V_n \equiv \{V_i\}_{i=1}^n$ are iid, independently generated from the sample $Z_n$, according to a random variable $V$ with bounded support, mean zero and variance one. This type of multiplicative bootstrap has been used in many problems involving empirical processes with a non-pivotal asymptotic distribution. See for instance Delgado and González-Manteiga (2000) or Scaillet (2005). In practice, $c_{n\alpha}$ is approximated as accurately as desired by $\eta^{*}_{n[B(1-\alpha)]}$, the $[B(1-\alpha)]$–th order statistic computed from $B$ replicates $\{\eta^{*}_{nj}\}_{j=1}^B$ of $\eta^{*}_n$. Equivalently, the test can be implemented using the bootstrap p-value $p^*_n = P_n(\eta^{*}_n > \eta_n)$, which is also approximated by Monte Carlo. Our bootstrap test rejects $H_0$ at the $\alpha$–th nominal level, $\alpha \in (0,1)$, when $\eta_n > c^{*}_{n\alpha}$, or equivalently $p^*_n < \alpha$. The next theorem states that the bootstrap test is consistent and has the right asymptotic size.

**Theorem 1** Assume that $F_X$ is continuous and $\{V_i\}_{i=1}^n$ are iid, independent of the sample $Z_n$, bounded and with mean zero and variance one. Then, for each $\alpha \in [0,1]$, 

(i) under $H_0$, $\lim_{n \to \infty} P(\eta_n > c^{*}_{n\alpha}) \leq \alpha$, with equality under the l.f.c;

(ii) under $H_1$, $\lim_{n \to \infty} P(\eta_n > c^{*}_{n\alpha}) = 1$.

Our methodology is directly applicable to testing second-order or, more generally, $j$–th order conditional stochastic dominance, $j \geq 2$, simply replacing the empirical process $C_n$ by

$$C_{n,j}(y, u) \equiv \frac{1}{n} \sum_{i=1}^n \left(1_{\{Y_i \leq y\}} - 1_{\{Y_i \geq y\}}\right) \left(u - F_X(X_i)\right)^j 1_{\{F_X(X_i) \leq u\}}, \ j \geq 2.$$ 

See e.g. McFadden (1989) for discussion of higher-order stochastic dominance.

The test is also applicable to testing inequality restrictions of general conditional moments, possibly indexed by parameters, and it can be accommodated to situations with multiple covariates. These applications are discussed in the next section.

**3. SOME APPLICATIONS OF THE BASIC FRAMEWORK**

**3.1. Conditional Moment Inequalities with Unknown Parameters**

We apply the basic framework to testing inequality restrictions on general conditional moments of functions of the observable variables, which may be indexed by
unknown parameters. That is, given a random vector $Z$ and a measurable function $m_\theta : \mathcal{X}_Z \to \mathbb{R}$ indexed by a vector of parameters $\theta \in \Theta$, where $\Theta \subseteq \mathbb{R}^k$ is a parameter space, the null hypothesis of interest is

$$H_0 : \mathbb{E}(m_{\theta_0}(Z) | X = x) \leq 0 \text{ for all } x \in \mathcal{W}_X \text{ and some } \theta_0 \in \Theta.$$  \hspace{1cm} (6)

Many applications fall under this setting. When $Z = (Y_1, Y_2, X)$ and $m_\theta (Z) = Y_1 - Y_2$, (6) is the hypothesis that a regression function dominates another. A version of the null hypothesis (6) is natural in treatment program evaluation. Let $D$ be an indicator of participation in the program, i.e. $D = 1$ if the individual participates in the treatment and $D = 0$ otherwise. Denote the observed outcome by $Y = Y (1) D + Y (0) (1 - D)$, where $Y (1)$ and $Y (0)$ are the potential outcomes of the individual in the treatment and control groups, respectively. We assume unconfoundedness or selection on observables, i.e. $Y (1)$ and $Y (0)$ are independent of $D$, conditional on the covariate $X$. The hypothesis of interest is that the treatment is beneficial for individuals with $x \in \mathcal{W}_X$, i.e.

$$\mathbb{E}(Y (0) | X = x) \leq \mathbb{E}(Y (1) | X = x), \quad \forall x \in \mathcal{W}_X.$$  \hspace{1cm} (7)

Let $q (x) \equiv \mathbb{E}(D | X = x)$ be the propensity score, and assume that $q \in (0, 1)$ a.s. In applied work, it is usually assumed that $q (x) = q_{\theta_0} (x)$ for some $\theta_0 \in \Theta \subseteq \mathbb{R}^p$, where $q_\theta$ is some cdf indexed by a vector of parameters $\theta$, e.g. a probit or a logit specification. Under these circumstances, using the fact that

$$\mathbb{E}((q_{\theta_0} (X) - D)Y | X = x) = \{\mathbb{E}(Y (0) | X = x) - \mathbb{E}(Y (1) | X = x)\} q_{\theta_0} (x) (1 - q_{\theta_0} (x)),$$

the hypothesis in (7) can be rewritten as $H_0$ in (6) with $Z = (Y, D, X)$ and $m_\theta (Z) = (q_\theta (X) - D) Y$. Lee and Whang (2009) and Hsu (2011) implement different tests for (7) based on smooth estimates of $E(Y (0) - Y (1) | X = x)$.

When $\theta_0$ is known, the basic framework presented in the previous section is directly applicable without changes. For any generic function $m : \mathcal{X}_Z \to \mathbb{R}^{d_m}$, we consider the test statistic

$$\bar{\eta}_{m,n} \equiv \sqrt{n} \max_{u \in \mathcal{U}_{X,n}} (T \bar{C}_{m,n} - \bar{C}_{m,n}) (u),$$
where
\[ \bar{C}_{m,n}(u) \equiv \frac{1}{n} \sum_{i=1}^{n} m(Z_i) (u - F_{X_n}(X_i)) 1_{\{F_{X_n}(X_i) \leq u\}}, \quad u \in [0, 1], \] (8)
estimates \( \bar{C}_m(u) \equiv \mathbb{E} \left( m(Z) (u - F_X(X)) 1_{\{F_X(X) \leq u\}} \right) \). When \( \theta_0 \) is known, tests based on \( \bar{m}_{\theta_0,n} \) are justified using the same arguments as in Theorem 1. Naturally, the stochastic dominance hypothesis between treatment and control groups conditional on the covariate \( X \) can be implemented by using \( Z = (Y, X, D) \) and \( m(Z) = (q_\theta(X) - D) 1_{\{Y \leq y\}} \), which is also indexed by \( y \in \mathcal{X}_Y \). A test for unconditional stochastic dominance has been recently proposed by Donald and Hsu (2011) based on the difference between the marginal distribution estimators of \( Y(0) \) and \( Y(1) \).

In many applications of practical relevance the moment function \( m_{\theta_0} \) involves an unknown parameter \( \theta_0 \). It happens when comparing productivity indexes, which are residuals of some production function estimate, see e.g. Delgado, Farinas and Ruano (2002). It also happens when testing treatment effects with an unknown propensity score. In randomized experiments \( D \) is independent of \( X \), and hence, \( q(x) \) is constant, say \( q(x) \equiv \theta_0 \). In this case, the parameter \( \theta_0 \) can be estimated by its sample analog \( \hat{\theta}_n = n^{-1} \sum_{i=1}^{n} D_i \), which is the relative frequency of participants in the treatment. When dealing with non-experimental data, i.e. if \( D \) and \( X \) are not mean-independent, \( q \) can be modeled by means of a discrete choice model depending on some unobserved latent variable, leading to \( q = q_{\theta_0} \) for some unknown \( \theta_0 \in \Theta \subset \mathbb{R}^p \).

Given iid observations \( \{Z_i\}_{i=1}^{n} \) of \( Z \), we assume that a \( \sqrt{n} - \) consistent estimator of \( \theta_0 \) is available, which satisfies the following assumption.

**Assumption E:** The estimator \( \hat{\theta}_n \) is strongly consistent for \( \theta_0 \) and satisfies the following linear expansion:
\[ \sqrt{n}(\hat{\theta}_n - \theta_0) = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} I_{\theta_0}(Z_i) + o_p(1), \]
where \( I_{\theta}(-) \) is such that: (i) \( \mathbb{E}(I_{\theta_0}(Z)) = 0 \) and \( I_{\theta_0} \equiv \mathbb{E}(I_{\theta_0}(Z)I_{\theta_0}(Z')) \) exists and is positive definite; and (ii) \( \lim_{\delta \to 0} \sup_{\theta \in \Theta_0, \|\theta - \theta_0\| \leq \delta} \mathbb{E}(\|I_{\theta}(Z) - I_{\theta_0}(Z)\|_2^2) = 0 \), where \( \Theta_0 \) is a neighborhood of \( \theta_0 \), \( \Theta_0 \subset \Theta \).

We also need some smoothness on \( m_{\theta} \). Define \( \tilde{m}_{\theta} \equiv \partial m_{\theta}/\partial \theta \) a.s.
ASSUMPTION S: The moment function \( m_\theta \) is a.s continuously differentiable in a neighborhood of \( \theta_0, \Theta_0 \subset \Theta \), with \( \mathbb{E} (|m_{\theta_0}(Z)|^2) < \infty \) and \( \mathbb{E} (\sup_{\theta \in \Theta_0} |\tilde{m}_\theta(Z)|) < \infty \).

These assumptions are fulfilled under mild moment conditions when, for example, \( m_\theta(Z) = \varepsilon_1 \theta_1(Z) - \varepsilon_2 \theta_2(Z) \) with \( \varepsilon_i \theta_i : X_Z \times \Theta \to \mathbb{R}, i = 1, 2 \), known functions and \( \theta = (\theta'_1, \theta'_2)' \). For example the \( \varepsilon_i \)'s may be the productivity indexes estimated as least squares residuals of a Cobb-Douglas production function. These assumptions are also fulfilled in randomized experiments by \( \theta_n = n^{-1} \sum_{i=1}^n D_i \), with \( l_\theta(Z) = (D - \theta) \) and \( \tilde{m}_\theta(Z) = Y \), provided \( 0 < \theta_0 < 1 \) and \( \mathbb{E}(Y^2) < \infty \).

Under these two assumptions and the l.f.c, we show in the Appendix that \( \tilde{C}_{m_\theta,n} \), defined as in (8), has the uniform in \( u \in U_X \) representation

\[
\tilde{C}_{m_\theta,n}(u) = \frac{1}{n} \sum_{i=1}^n \left\{ m_{\theta_0}(Z_i) (u - F_X(X_i)) 1\{F_X(X_i) \leq u\} + V_{\theta_0}(Z_i) \tilde{C}_{\tilde{m}_\theta}(u) \right\} + O_p \left( n^{-1/2} \right).
\]

This uniform expansion suggests a simple bootstrap approximation based on

\[
\tilde{C}_{m_\theta,n}^*(u) = \frac{1}{n} \sum_{i=1}^n \left\{ m_{\theta_n}(Z_i) ((u - F_{X_n}(X_i)) 1\{F_{X_n}(X_i) \leq u\} + V_{\theta_n}(Z_i) \tilde{C}_{\tilde{m}_\theta,n}(u) \right\} V_i,
\]

where \( \{V_i\}_{i=1}^n \) are iid generated as indicated in Theorem 1. Let \( \tilde{\eta}_{m_\theta,n}^* \) be the bootstrap test statistic based on \( \tilde{C}_{m_\theta,n}^* \), and denote by \( \tilde{c}_{\alpha,n}^* \) the corresponding bootstrap critical value. Our next result is the analog of Theorem 1 in the current setting.

**Theorem 2** Let the assumptions of Theorem 1, E and S hold. Then,

(i) under \( H_0 \), \( \lim_{n \to \infty} \mathbb{P} \left( \tilde{\eta}_{m_\theta,n} > \tilde{c}_{\alpha,n}^* \right) \leq \alpha \), with equality under the l.f.c;

(ii) under \( H_1 \), \( \lim_{n \to \infty} \mathbb{P} \left( \tilde{\eta}_{m_\theta,n} > \tilde{c}_{\alpha,n}^* \right) = 1. \)

### 3.2. Multiple Covariates.

In this subsection we consider testing \( H_0 \) with \( X \) a \( d \)-dimensional covariate. We discuss two approaches. The first approach is based on the fact that the null hypothesis implies that for all \( \beta \in \mathbb{S}^d \equiv \{ \beta \in \mathbb{R}^d : \beta'\beta = 1 \} ,

\[
F_{Y_i|\beta'X}(y, \beta'x) \leq F_{Y_i|\beta'X}(y, \beta'x) \text{ for all } (y, x) \in \mathcal{W}_Y \times \mathcal{W}_X.
\]

(10)
Escanciano (2006) considered a similar approach for the problem of testing the lack-of-fit of a regression model, and Kim (2008) has also used this approach for inferences under conditional moment inequalities. For each fixed \( \beta \in \mathbb{S}^d \), let \( \hat{\eta}_n(\beta) \) denote the test statistic in (5) using the sample \( \{Y_{i1}, Y_{2i}, \beta'X_i\}_{i=1}^n \). The test statistic for (10) is \( \int_{\mathbb{S}^d} \hat{\eta}_n(\beta) d\beta \). In applications, computing the integral can be a cumbersome task. For that reason, we propose the Monte Carlo approximation \( \hat{\eta}_{n,m} \equiv m^{-1} \sum_{j=1}^m \hat{\eta}_n(\beta_j) \), where \( \{\beta_j\}_{j=1}^m \) is a sequence of \( iid \) variables from a uniform distribution in \( \mathbb{S}^d \), with \( m \to \infty \) as \( n \to \infty \). The sequence \( \{\beta_j\}_{j=1}^m \) can be easily generated from a \( d \)-dimensional vector of standard normals, scaled by its norm. Alternatively, the researcher may be interested in particular choices of \( \beta_j \). For instance, \( \beta_j = (1, 0, ..., 0) \in \mathbb{S}^d \) leads to a test focusing on the conditional distributions of \( Y_k \), \( k = 1, 2 \), given the first component of \( X \).

The limit distribution of \( \hat{\eta}_{n,m} \) under the l.f.c can be approximated by the bootstrap distribution of \( m^{-1} \sum_{j=1}^m \hat{\eta}_n^*(\beta_j) \), where \( \hat{\eta}_n^*(\beta_j) \) is the bootstrap approximation suggested in Section 2, using the same sequence \( V_n \) for \( j = 1, ..., m \). The validity of the resulting bootstrap test follows from combining the empirical processes tools in Escanciano (2006) with our results of Section 2 in a routine fashion.

Alternatively, following a traditional approach in multivariate modeling, see the projection pursuit idea of Friedman and Tukey (1974), we could consider the composite hypothesis,

\[
H_0 : F_{Y_{i1}|\beta_0'X}(y, \beta_0'x) \leq F_{Y_{2i}|\beta_0'X}(y, \beta_0'x) \quad \text{for all } (y, x) \in \mathcal{W}_Y \times \mathcal{W}_X,
\]

where \( \beta_0 \) is an unknown \( d \)-dimensional parameter, \( \beta_0 \in \Theta \subset \mathbb{R}^d \). For instance, such situation arises in treatment effects when the conditional distribution of \( (Y, D) \) given \( X \) satisfies a single-index restriction, i.e. \( F_{(Y,D)|X}(y, d) = F_{(Y,D)|\beta_0'X}(y, d) \) for some \( \beta_0 \in \Theta \subset \mathbb{R}^d \). A test for the composite hypothesis can be constructed based on \( \hat{\eta}_n(\beta_n) \) where \( \beta_n \) is a consistent estimator of \( \beta_0 \) obtained from the single-index restriction, e.g. by average derivative or semiparametric least squares methods. The parameter \( \beta_0 \) is only identified up to scale; so some normalization is in general needed. Here, it is technically convenient to normalize the first component of \( \beta \in \Theta \) to 1. In particular,
we assume $\beta_{01} = 1$. Furthermore, we also assume that this coefficient corresponds to a continuous component $X_1$ of $X = (X_1, X_{-1})$, where $X_{-1} \equiv (X_2, ..., X_d)$. The following assumption requires smoothness for the conditional distribution of $X_1$ given $X_{-1}$.

**Assumption M:** The conditional distribution of $X_1$ given $X_{-1}$ has a (uniformly) bounded Lebesgue density. Furthermore, $\mathbb{E}(|X|^2) < \infty$ and the parameter space $\Theta$ is compact.

We now show that under some mild regularity conditions $\hat{\eta}_n(\beta_n)$ and $\hat{\eta}_n(\beta_0)$ have the same asymptotic distribution under the l.f.c. That is, asymptotically, the estimated parameters $\beta_n$ do not have any effect on the limiting distribution under l.f.c. See Stute and Zhu (2005) for a related result in a different context. The bootstrap consistency of the test in this single-index model follows combining our results in Theorem 1 and the next Theorem in a routine fashion.

**Theorem 3** Let Assumption M hold. Then, under the l.f.c in (11), if $\beta_n$ is a consistent estimator of $\beta_0$, then

$$\hat{\eta}_n(\beta_n) = \hat{\eta}_n(\beta_0) + o_p(1).$$

Theorem 3 also holds if we replace the index $\beta_{0x}$ by a general parametric index $v(\beta_0, x)$, without significant changes in the proof. For instance, we could take $v(\beta_0, x) = q_{\theta_0}(x)$ and $\beta_0 = \theta_0$ in the treatment effects example, which is often used in applications. Furthermore, this result is also valid for more general index functions, including semiparametric or nonparametric ones, but formally proving this is beyond the scope of this article. The result in Theorem 3 is particularly convenient for ease of implementation of our test, as there is no need for re-estimating the parameters $\beta_0$ in each bootstrap iteration, or estimating the influence function of the estimator $\beta_n$. Given data $\{Z_i\}_{i=1}^n$, we estimate consistently $\beta_0$, and then apply the test statistic of Section 2 to $\{Y_{i1}, Y_{2i}, \beta_n^i, X_i\}_{i=1}^n$, using the same multiplier-type bootstrap.
4. EMPIRICAL RESULTS

4.1. Monte Carlo Simulations.

This section illustrates the finite sample performance of the tests by means of simulations and an application to testing treatment effects. The \( \{V_i\}_{i=1}^{n} \) used in the bootstrap implementation are independently generated as \( V \) with \( P(V = 1 - \varphi) = \varphi/\sqrt{5} \) and \( P(V = \varphi) = 1 - \varphi/\sqrt{5} \), where \( \varphi = (\sqrt{5} + 1)/2 \). See Mammen (1993) for motivation on this popular choice. The bootstrap critical values are approximated by Monte Carlo using 1,000 replications and the simulations are based on 10,000 Monte Carlo Experiments. We report rejection probabilities at 10%, 5% and 1% significance levels.

We first investigate the size accuracy and power of the proposed conditional stochastic dominance tests for the following designs:

(i) \( Y_1 = 1 + \varepsilon^{(1)}; Y_2 = 1 + \varepsilon^{(2)} \),

(ii) \( Y_1 = \exp(X) + \varepsilon^{(1)}; Y_2 = \exp(X) + \varepsilon^{(2)} \),

(iii) \( Y_1 = \sin(2\pi X) + \varepsilon^{(1)}; Y_2 = \sin(2\pi X) + \varepsilon^{(2)} \),

(iv) \( Y_1 = 1 + \varepsilon^{(1)}; Y_2 = 1 + X + \varepsilon^{(2)} \),

(v) \( Y_1 = \exp(X) + \varepsilon^{(1)}; Y_2 = \exp(X) + X + \varepsilon^{(2)} \),

(vi) \( Y_1 = \sin(2\pi X) + \varepsilon^{(1)}; Y_2 = \sin(2\pi X) + X + \varepsilon^{(2)} \),

(vii) \( Y_1 = 1 + \varepsilon^{(1)}; Y_2 = \sin(2\pi X) + \varepsilon^{(2)} \),

(viii) \( Y_1 = \exp(X) + \varepsilon^{(1)}; Y_2 = \exp(X) + \sin(2\pi X) + \varepsilon^{(2)} \),

(ix) \( Y_1 = \sin(2\pi X) + \varepsilon^{(1)}; Y_2 = 2 \sin(2\pi X) + \varepsilon^{(2)} \),

where \( X \) is distributed as \( U[0,1] \), independently of the normal errors \( \varepsilon^{(1)} \) and \( \varepsilon^{(2)} \), which are independent, have zero mean, and variance \( \sigma^2 = 1/4 \). Similar designs were used in Neumeyer and Dette (2003) for testing the equality of regression functions in
a two sample context. Table 1 reports the proportion of rejections for models (i)-(ix) and sample sizes $n = 50$ and 150.

**TABLE 1 ABOUT HERE**

Models (i)-(iii) fall under the null hypothesis. We observe that our bootstrap test exhibits good size accuracy, even when $n = 50$. The power is moderate for $n = 50$ under alternatives (iv)-(viii), and uniformly high for any alternative with $n = 150$. The highest power is achieved for the alternative (ix), where the regression functions cross at one point.

In the second experiment, we study the finite sample performance of the stochastic dominance test applied to multivariate covariates with index restrictions. The designs are those of models (ii, iii) (under null) and models (v,vi, viii and ix) (under the alternative), where $X$ is replaced by the index $\beta'_0X \equiv X_1 + X_2 + X_3$, where $X_j$, $j = 1, 2$ and 3, are mutually independently distributed as $U[0, 1]$, and also independent of the normal errors $\varepsilon^{(1)}$ and $\varepsilon^{(2)}$. The methodology is applied following a two-step approach. In the first step, the unknown parameter $\beta_0 = (1, 1, 1)'$ is estimated from the data $\{(Y_{1i}, X_i)\}_{i=1}^n$ by the minimum average variance estimator (MAVE) proposed in Xia, Tong, Li and Zhu (2002) and denoted by $\beta_n$. We implement the MAVE with a Gaussian kernel and a cross-validation method for choosing the bandwidth parameter. In a second step, the test is applied to the data $\{(Y_{1i}, Y_{2i}, \beta'_nX_i)\}_{i=1}^n$, as in the univariate case. Table 2 reports the proportion of rejections for sample sizes $n = 50$ and 150.

**TABLE 2 ABOUT HERE**

The size performance for models (ii)-(iii) is excellent for small sample sizes as $n = 50$. The obtained results support our asymptotic analysis. The estimation of $\beta_0$ does not have an impact in the finite sample distribution, in agreement with the asymptotic equivalence of Theorem 3. Relative to the first set of experiments, the empirical power is higher for models (v)-(vi), and lower for (viii)-(ix), which is due to the additional uncertainty in the semiparametric estimation of the index parameter $\beta_0$. This second set of simulations confirms our theoretical results – estimation of the
nuisance parameter $\beta_0$ does not affect the asymptotic distribution of our test under
the l.f.c, but it may affect the power performance. It is remarkable that with a small
sample size as $n = 50$ the asymptotic result already provides a good approximation of
the finite sample distribution in a semiparametric context in which infinite dimensional
estimation is involved.

In our third experiment, we study the finite sample performance of the treatment
effects test discussed in Subsection 3.1. We consider the design,

$$
Y (0) = 1 - X + \varepsilon^{(1)},
$$

$$
Y (1) = 1 - c + (4c^2 - 1)X + cX^2 + \varepsilon^{(2)},
$$

where $X, \varepsilon^{(1)}$ and $\varepsilon^{(2)}$ are generated as independent $U[0,1]$ variables, and $c$ is a posi-
tive constant. The treatment indicator is generated as $D = 1\{U^{(3)} \leq U^{(4)}\}$, where
$U^{(3)}$ and $U^{(4)}$ are independent copies of $\varepsilon^{(1)}$ and $\varepsilon^{(2)}$. The observed outcome is
$Y = Y (1) D + Y (0) (1 - D)$. The l.f.c. corresponds to $c = 0$ and, as $c$ increases,
the design deviates from the null in a direction somewhat similar to that observed in
the empirical application in Subsection 4.2.

The top panel of Figure 1 reports the percentage of rejections as a function of $c$,
for values of $c$ from 0 to 2 at intervals of 0.25, and with $n = 100$ and 300. For $c = 0$,
the size accuracy is excellent, with a proportion of rejections, when $n = 100$, of 1.1%,
5.1% and 10.1% at 1%, 5% and 10% of significance, respectively. The empirical power
is non-decreasing in $c$, is low for $c = 0.25$, detects alternatives with $c \geq 0.5$, and
stabilizes for $c \geq 0.75$.

In the fourth experiment, we relax the conditional mean independence between $D$
and $X$, and generate data from (12) but with $D = 1\{\alpha_0 + \beta_0 X \leq \varepsilon\}$, where
$\theta_0 \equiv (\alpha_0, \beta_0) = (1, 0.2)$ is assumed to be unknown, and $\varepsilon$ follows a standard normal distribution,
independently of the standard normal covariate $X$ and the errors $\varepsilon^{(1)}$ and $\varepsilon^{(2)}$. The
propensity score is modeled by a probit model, and the parameter $\theta_0$ is estimated by
the conditional maximum likelihood estimator. The bottom panel of Figure 1 reports
the percentage of rejections as a function of $c$, for sample sizes $n = 100$ and 300.
The results for the non-randomized experiment with a probit propensity score are
qualitatively the same as for the randomized experiment.

**FIGURE 1 ABOUT HERE**

Overall, the simulations show that the proposed bootstrap tests exhibit fairly good size accuracy and power for relatively small sample sizes, with uniform power across all alternatives considered.

**4.2. An Application to Experimental Data.**

We apply the proposed testing method to studying the effectiveness of the National Supported Work (NSW) Demonstration program. The NSW was a randomized, temporary employment program carried out in the U.S. during the mid-1970s to help disadvantaged workers. In an influential article, Lalonde (1986) used the NSW experimental data to examine the performance of alternative statistical methods for analyzing non-experimental data. Variations and subsamples of this data set were later reanalyzed by Dehejia and Wahba (1999), among others. We use the original data for males in Lalonde (1986) to illustrate our procedure. For a comprehensive description of the experimental data see Lalonde (1986) and Dehejia and Wahba (1999).

The data consist of 297 treatment group observations and 425 control group observations. Our dependent variable $Y$ is the increment in earnings, measured in 1982 dollars, between 1978 (post-intervention year) and 1975 (pre-intervention year). To illustrate our methods we choose as independent variable $X$ age. Figure 2 plots the kernel regression estimates for the period 1975-1978 with age restricted to its 10% and 90% quantiles in order to avoid boundary biases. We used a Gaussian kernel with bandwidth values 1 and 2 for the control and treatment groups, respectively. Cross-validation led to smaller bandwidths of 0.55 and 1.38, respectively, which imply under-smoothing. Nonparametric smoothed estimates suggest a positive treatment, specially for old workers. Parametric tests carried out in Lalonde (1986) for significance of the unconditional average treatment effect also indicated a positive effect.

**FIGURE 2 ABOUT HERE**
The null hypothesis of non-negative conditional mean treatment effect is considered, as in (7). The treatment was randomized, and hence, our hypothesis corresponds to (6) with \( m_{\theta_0}(Z) = (\theta_0 - D)Y \), where \( \theta_0 = \mathbb{E}(D) \) is consistently estimated by \( \theta_n = n^{-1} \sum_{i=1}^{n} D_i \). The test statistic is implemented as in Section 3.1. In Table 3 we report the bootstrap p-values over 10,000 bootstrap replications of our test for several values of \( a_l \) in \( W_X = [a_l, 55] \). The value \( a_l = 17 \) corresponds to the full support of age in the data. Table 3 also contains the sample sizes of the control and treatment groups, \( n_1 \) and \( n_0 \), respectively.

As evidenced from Table 3, our test rejects the null hypothesis of non-negative impact of the NSW program at 5% when the whole age distribution is included (\( a_l = 17 \)). Our results, in contrast with previous findings in the literature, provide evidence of treatment effect heterogeneity in age. Lee and Whang (2009) use the same data set and fail to reject the null hypothesis of non-negative conditional treatment effect using a test based on the \( L_1 \)-distance of smoothed estimates of \( E(Y(0) - Y(1)|X = x) \) and the space of non-positive functions. Figure 2 and Table 3 suggest that the rejection is due to young individuals between 17 and 21 years old for whom the job training program was not beneficial, as measured by the incremental earnings between post-intervention and pre-intervention years. This feature of the data is missed by methods using smoothers because their lack of precision in the tails of the age distribution imply a lack of power against small deviations of the null in the direction observed in this data.

For completeness, we have also applied the conditional stochastic dominance test for the whole distribution, i.e. using \( m_{\theta_0}(Z) = (D - \theta_0)1_{\{Y \leq y\}} \), which is also indexed by \( y \in \mathcal{X}_Y \). The results are reported in Table 3. The test does not reject this hypothesis. That is, we reject the hypothesis that the treatment group dominates the control group in terms of the conditional means, but we cannot reject the stochastic dominance hypothesis in terms of the whole distribution. Notice that this does not lead to contradictory results. We can also arrive to the same conclusion in a pure parametric
setting. For instance, when comparing confidence intervals and confidence ellipses on parameter restrictions, i.e., we can reject a significance hypothesis on different single parameters, but we may be unable to reject the joint significance hypothesis on these parameters.

To check the robustness of the previous results to the inclusion of other covariates in the NSW study we consider a single-index semiparametric specification as in Section 3.2. The covariates in the NSW study are, in addition to age, educ=years of schooling; black=1 if black, 0 otherwise; hisp=1 if Hispanic, 0 otherwise; married=1 if married, 0 otherwise; and ndegr=1 if no high school degree, 0 otherwise. We specify \( E(Y|X) = E(Y|\beta_0X) \), and estimate the parameter \( \beta_0 \) by the MAVE proposed in Xia, Tong, Li and Zhu (2002), which allows continuous and discrete covariates. We implement the MAVE with a Gaussian kernel and a cross-validation method for choosing the bandwidth parameter. The bootstrap p-values obtained from 10,000 replications are reported in the third column of Table 3. For a better comparison with the previous results, we consider the same subsamples, divided according to age. The null hypothesis is still rejected when considering the full range of the age distribution, but the test does not reject when considering subsamples with individuals older than 18 years old. In view of the previous results, the latter is likely to be driven by a decrease in precision because of the semiparametric smoothed estimation involved.

5. CONCLUSIONS AND SUGGESTIONS FOR FURTHER WORK.

This article has proposed a methodology for testing one-sided conditional moment restrictions, with two distinctive features. On one hand, the tests can be implemented under minimal requirements on the smoothness of the underlying nonparametric curves and without resorting to smooth estimation. On the other hand, the new tests can be easily computed using the efficient PAVA algorithm, already implemented in many statistical packages. We have shown how the proposed methods can be applied to accommodate composite hypotheses of different nature and multiple covariates. Finally, we have illustrated the practical usefulness of our methods with an application to evaluating treatment effects in social programs.
Our basic results can be extended to other situations of practical interest. For instance, a straightforward extension of our results consists of allowing serial dependent observations. This has important applications in a number of settings, see e.g. tests of superior predictive ability in Hansen (2005). The extension to time series does not pose any additional difficulties, as long as the the weak convergence of the process \( \sqrt{n}C_n \) holds. There is, however, an extensive literature providing sufficient conditions for weak convergence of empirical processes under weak dependence, see e.g. Linton, Maasoumi and Whang (2005) and Scaillet and Topaloglou (2010) for applications in the context of stochastic dominance testing.

In the rest of this section, we discuss extensions of the basic framework to cases where smoothing cannot be avoided. Most notably, the conditional stochastic dominance test can also be applied when the covariate observations are different in each sample by introducing covariate-matching techniques. See e.g. Hall and Turlach (1997), Hall, Huber and Speckman (1997), Koul and Schick (1997, 2003), Cabus (1998), Neumeyer and Dette (2003), Pardo-Fernández, van Keilegom and González-Manteiga (2007) or Srihera and Stute (2010). These techniques use smooth estimators, typically kernels. In particular, proposals by Cabus (1998) and Neumeyer and Dette (2003), designed for testing the equality of nonparametric regression curves in a two sample context, can be accommodated to one-sided testing by applying the methodology presented in this article.

Another important extension would consist of allowing the function \( m_\theta \) in (6) to be indexed by an infinite-dimensional nuisance parameter \( \theta \). For instance, this is the case in the context of non-experimental treatment effects when the propensity score \( q \) is nonparametrically specified. When \( \theta_0 \) is a nonparametric function estimated by kernels, or other smoothing techniques, the corresponding \( \tilde{C}_{m_{\theta_0,n}} \) is asymptotically equivalent to a \( U \)-process under the l.f.c. The test can also be implemented in this case by means of a multiplier bootstrap on the Hoeffding projection, along the lines suggested by Delgado and González-Manteiga (2001). A detailed analysis of these extensions is beyond the scope of this article and is deferred to future work.
APPENDIX

Before proving the main results of the article, we first introduce some notation. For a generic set $G$, let $\ell^\infty(G)$ be the Banach space of all uniformly bounded real functions on $G$ equipped with the uniform metric $\|f\|_G \equiv \sup_{z \in G} |f(z)|$. In this article we consider convergence in distribution of empirical processes in the metric space $(\ell^\infty(G), \|\cdot\|_G)$ in the sense of J. Hoffmann-Jørgensen (see, e.g., van der Vaart and Wellner, 1996). For any generic Euclidean random vector $\xi$ on a probability space $(\Omega, \mathcal{A}, \mathbb{P})$, $\chi_\xi$ denotes its state space and $P_\xi$ its induced probability measure with corresponding distribution function $F_\xi(\cdot) = P_\xi(-\infty, \cdot]$. Given iid observations $\{\xi_i\}_{i=1}^n$ of $\xi$, $\mathbb{P}_{\xi_n}$ denotes the empirical measure, which assigns a mass $\frac{1}{n}$ to each observation, i.e. $\mathbb{P}_{\xi_n} f = \frac{1}{n} \sum_{i=1}^n f(\xi_i)$. Let $F_{\xi_n}(\cdot) \equiv \mathbb{P}_{\xi_n}(-\infty, \cdot]$ be the corresponding empirical cdf. Likewise, the expectation is denoted by $\mathbb{E}_{\xi_n} f = \int f dP_{\xi_n}$. The empirical process evaluated at $f$ is $G_{\xi_n} f$ with $G_{\xi_n} \equiv \sqrt{n}(\mathbb{P}_{\xi_n} - P_{\xi})$. Let $\|\cdot\|_{2,P}$ be the $L_2(P)$ norm, i.e. $\|f\|_{2,P}^2 = \int f^2 dP$. When $P$ is clear from the context, we simply write $\|\cdot\|_2 \equiv \|\cdot\|_{2,P}$. Let $|\cdot|$ denote the Euclidean norm, i.e. $|A|^2 = A^\top A$. For a measurable class of functions $G$ from $X$ to $\mathbb{R}$, let $||\cdot||$ be a generic pseudo-norm on $G$, i.e. a norm except for the property that $\|f\| = 0$ does not necessarily imply that $f \equiv 0$. Let $N(\varepsilon, G, ||\cdot||)$ be the covering number with respect to $||\cdot||$, i.e. the minimal number of $\varepsilon$-balls with respect to $||\cdot||$ needed to cover $G$. Given two functions $l, u \in G$ the bracket $[l, u]$ is the set of functions $f \in G$ such that $l \leq f \leq u$. An $\varepsilon$-bracket with respect to $||\cdot||$ is a bracket $[l, u]$ with $|l - u| \leq \varepsilon$. The covering number with bracketing $N_{[\cdot]}(\varepsilon, G, ||\cdot||)$ is the minimal number of $\varepsilon$-brackets with respect to $||\cdot||$ needed to cover $G$. Let $\mathcal{H}_B$ be the collection of all non-decreasing functions $F : \mathbb{R} \rightarrow [0, 1]$ of bounded variation less or equal than 1, and define $\Pi \equiv [-\infty, \infty] \times [0, 1]$. Finally, throughout $K$ is a generic positive constant that may change from expression to expression.

We first state an auxiliary result from the empirical process literature. Define the generic class of measurable functions $G \equiv \{Z \rightarrow m(Z, \theta, h) : \theta \in \Theta, h \in \mathcal{H}\}$, where $\Theta$ and $\mathcal{H}$ are endowed with the pseudo-norms $|\cdot|_{\Theta}$ and $|\cdot|_{\mathcal{H}}$, respectively. The following result is part of Theorem 3 in Chen, Linton and van Keilegom (2003).
Lemma A1: Assume that for all \((\theta_0, h_0) \in \Theta \times \mathcal{H}\), \(m(Z, \theta, h)\) is locally uniformly \(L_2(P)\) continuous, in the sense that
\[
\mathbb{E} \left[ \sup_{\theta:|\theta - \theta_0| < \delta, \mathbb{h}:|\mathbb{h} - h_0| < \delta} |m(Z, \theta, h) - m(Z, \theta_0, h_0)|^2 \right] \leq K\delta^s,
\]
for all sufficiently small \(\delta > 0\) and some constant \(s \in (0, 2]\). Then,
\[
N_1(\varepsilon, \mathcal{G}, \|\cdot\|_2) \leq N \left( \left( \frac{\varepsilon}{2K} \right)^{2/s}, \Theta, \|\cdot\|_\Theta \right) \times N \left( \left( \frac{\varepsilon}{2K} \right)^{2/s}, \mathcal{H}, \|\cdot\|_\mathcal{H} \right).
\]

Proof of Theorem 1: Throughout \(Z_i \equiv (Y_{1i}, Y_{2i}, X_i)\), \(i \geq 1\), \(\bar{Z} \equiv (\bar{y}_1, \bar{y}_2, \bar{x}) \in \chi_Z\). Let \(\bar{C}_n\) be defined as \(C_n\) but with \(F_{X_n}\) replaced by the true cdf \(F_X\). Set \(\Delta_n \equiv \sqrt{n}(TC_n - C_n)\), and similarly define \(\check{\Delta}_n\) with \(\check{C}_n\) replacing \(C_n\). The proof of Theorem 1(i) follows three steps: first, we prove that tests based on \(\Delta_n\) and \(\check{\Delta}_n\) are asymptotically equivalent under the l.f.c, that is,
\[
\sup_{(y, u) \in \mathcal{W}_Y \times \mathcal{U}_{X_n}} \Delta_n(y, u) = \sup_{(y, u) \in \mathcal{W}_Y \times \mathcal{U}_{X_n}} \check{\Delta}_n(y, u) + o_P(1). \tag{13}
\]
Second, we prove that the supremum in \(\mathcal{U}_{X_n}\) in the test statistic can be replaced by a supremum in \(\mathcal{U}_X\), that is,
\[
\sup_{(y, u) \in \mathcal{W}_Y \times \mathcal{U}_{X_n}} \check{\Delta}_n(y, u) = \sup_{(y, u) \in \mathcal{W}_Y \times \mathcal{U}_X} \check{\Delta}_n(y, u) + o_P(1). \tag{14}
\]
Finally, we prove the asymptotic behaviour of the test under \(H_0\) and \(H_1\), not just under the l.f.c.

We proceed with the proof of (13). To that end, we shall prove that \(\check{C}_n\) and \(C_n\) are asymptotically equivalent under the l.f.c. First, define the classes of functions
\[
\mathcal{G}_1 \equiv \{(\bar{y}_1, \bar{y}_2) \in \chi_{Y_1} \times \chi_{Y_2} \rightarrow \Delta_y(\bar{y}_1, \bar{y}_2) \equiv 1_{\{\bar{y}_1 \leq y\}} - 1_{\{\bar{y}_2 \leq y\}} : y \in [-\infty, \infty]\}
\]
and
\[
\mathcal{G}_2 \equiv \{\bar{x} \in \chi_X \rightarrow f_{u,F}(\bar{x}) \equiv (u - F(\bar{x}))1_{\{F(\bar{x}) \leq u\}} : u \in [0, 1], \ F \in \mathcal{H}_B\}.
\]
Define the product class \(\mathcal{H} \equiv \mathcal{G}_1 \cdot \mathcal{G}_2\), and notice that \(\check{C}_n(y, u) = \mathbb{P}_{Z_n}h_{y,u,F_X}\), where
\[
h_{y,u,F}(\bar{z}) \equiv \{1_{\{\bar{y}_1 \leq y\}} - 1_{\{\bar{y}_2 \leq y\}}\} (u - F(\bar{x}))1_{\{F(\bar{x}) \leq u\}}.
\]
belongs to $\mathcal{H}$. We prove that $\mathcal{H}$ is $P_Z$-Donsker. By Example 2.10.8 in van der Vaart and Wellner (1996) and the fact that $\mathcal{G}_1$ is $P_Z$-Donsker it suffices to prove that $\mathcal{G}_2$ is $P_Z$-Donsker. To that end, note that for each $(u, F) \in [0,1] \times \mathcal{H}_B$, using the triangle inequality and the simple inequality $|a_+ - b_+|^2 \leq |a - b|^2$ for all $a, b \in \mathbb{R}$, where $a_+ = \max\{a, 0\}$, we obtain

$$\mathbb{E} \left[ \sup |f_{u_1, F_1}(X) - f_{u, F}(X)|^2 \right] \leq K \delta^2,$$

where the supremum is over the set $u_1 \in [0,1]$ and $F_1 \in \mathcal{H}_B$ such that $|u_1 - u| \leq \delta$ and $\sup_{x \in \mathbb{R}} |F_1(x) - F(x)| \leq \delta$, respectively. By Lemma A1 and Theorem 19.5 in van der Vaart (1998), the class $\mathcal{G}_2$, and hence $\mathcal{H}$, is $P_Z$-Donsker.

Thus, by a stochastic equicontinuity argument and the Glivenko-Cantelli theorem

$$\sup_{(y,u) \in \Pi} \left| G_{Z_n} h_{y,u,F_{X_n}} - G_{Z_n} h_{y,u,F_X} \right| \to_p 0.$$

Furthermore, since under the l.f.c $P_Z h = 0$, for all $h \in \mathcal{H}$,

$$\sup_{(y,u) \in \Pi} \left| P_{Z_n} h_{y,u,F_{X_n}} - P_{Z_n} h_{y,u,F_X} \right| = o_P \left( n^{-1/2} \right),$$

and hence,

$$\sup_{(y,u) \in \Pi} \left| C_n (y,u) - C_n (y,u) \right| = o_P \left( n^{-1/2} \right). \quad (15)$$

In order to prove (13), we must show the continuity in the metric space $(\ell^\infty(\Pi), \| \cdot \|_\Pi)$ of the functional $\varphi : \ell^\infty(\Pi) \mapsto \mathbb{R}^+$ defined as

$$\varphi(f) \equiv \sup_{(y,u) \in \Pi} (T f - f)(y,u).$$

To that end, note that Lemma 2.2 in Durot and Tocquet (2003) implies that for each $f, g \in \ell^\infty(\Pi)$,

$$\sup_{u \in [0,1]} |(T f - T g)(y,u)| \leq \sup_{u \in [0,1]} |(f - g)(y,u)| \text{ for each } y \in \mathbb{R} \text{ fixed.}$$

Since the last inequality holds for all $y \in \mathbb{R}$, for any $f, g \in \ell^\infty(\Pi)$,

$$|\varphi(f) - \varphi(g)| \leq \|T f - T q\|_\Pi + \|f - g\|_\Pi$$

$$\leq 2 \|f - g\|_\Pi,$$
which shows that $\varphi$ is continuous with respect to $\|\cdot\|_\Pi$. Then, (13) follows from (15) and the continuity of $\varphi$.

We now prove (14) under the l.f.c. We have shown above that $\mathcal{H}$ is a Donsker class, i.e. $\mathcal{G}_n$ converges in distribution to a $P_Z$-bridge as a random element of $(\ell^\infty(\mathcal{H}), \|\cdot\|_\mathcal{H})$, which in turn implies that $\tilde{C}_n(y, u) = \mathbb{P}_n h_{y, u, F_X}$, and hence $C_n$ by (15), converges in distribution under the l.f.c to a tight Gaussian process $C_\infty$ in $\ell^\infty(\Pi)$ with zero mean and covariance function
\[
K(v_1, v_2) \equiv \mathbb{E}(h_{v_1, F_X}(Z) h_{v_2, F_X}(Z)), \quad v_j = (y_j, u_j), \quad j = 1, 2. \tag{16}
\]
In particular, these arguments prove that $\tilde{\Delta}_n$ is stochastically equicontinuous in $\ell^\infty(\Pi)$ with respect to the pseudo-metric $\|\cdot\|_2$. Hence, from the triangle inequality, the equicontinuity of $\tilde{\Delta}_n$ and the Glivenko-Cantelli theorem,
\[
\sup_{(y, u) \in \mathcal{W}_Y \times \mathcal{U}_X} \tilde{\Delta}_n(y, u) - \sup_{(y, u) \in \mathcal{W}_Y \times \mathcal{U}_X} \tilde{\Delta}_n(y, u) = \left| \sup_{(y, x) \in \mathcal{W}_Y \times \mathcal{W}_X} \tilde{\Delta}_n(y, F_X(x)) - \sup_{(y, x) \in \mathcal{W}_Y \times \mathcal{W}_X} \tilde{\Delta}_n(y, F_X(x)) \right| \\
\leq \left| \sup_{(y, x) \in \mathcal{W}_Y \times \mathcal{W}_X} \tilde{\Delta}_n(y, F_X(x)) - \tilde{\Delta}_n(y, F_X(x)) \right| \\
\leq \sup_{y \in \mathcal{W}_Y, |u - u'| \leq \delta_n} \left| \tilde{\Delta}_n(y, u) - \tilde{\Delta}_n(y, u') \right| \\
= o_p(1),
\]
where $\delta_n \equiv \sup_{x \in \mathcal{W}_X} |F_X(x) - F_X(x)|$.

Hence, by (13)-(14) and the continuous mapping theorem, $\eta_n$ converges in distribution under the l.f.c. to
\[
\varphi(C_\infty) \equiv \sup_{(y, u) \in \mathcal{W}_Y \times \mathcal{U}_X} (TC_\infty - C_\infty)(y, u).
\]
We now study the behaviour of the test, not just under the l.f.c, but under $H_0$ and the alternative hypothesis. To that end, we define $G_n \equiv C_n - C$. Then, by definition of the l.c.m the function $TG_n(y, \cdot) + C(y, \cdot)$ is above $C_n(y, \cdot)$ and is concave in $u \in \mathcal{U}_X$ under $H_0$, since both $TG_n(y, \cdot)$ and $C(y, \cdot)$ are concave. Hence, $TG_n + C$ is uniformly above $TC_n$. Thus, under $H_0$,
\[
\sqrt{n}(TC_n - C_n) \leq \sqrt{n}(TG_n - G_n). \tag{17}
\]
Under the l.f.c $C(y, u) \equiv 0$, and hence $G_n = C_n$, so (17) becomes an equality.

Now, the multiplier functional limit theorem (Theorem 2.9.6 in van der Vaart and Wellner, 1996) and the continuous mapping theorem imply that, for all $x \geq 0$,

$$
\mathbb{P}_n^* (\eta_n^* > x) \to_{a.s.} 1 - F_\varphi(x),
$$

where $F_\varphi$ is the cdf of $\| \sqrt{n} (TG_n - G_n) \|_{W_Y \times U_X}$, with $G_\infty$ a tight Gaussian process in $\ell^\infty (W_Y \times U_X)$ with zero mean and covariance function (16). Being the cdf of a continuous mapping of a Gaussian process, $F_\varphi$ is continuous, see Lifshits (1982).

Hence, by (17), under $H_0$,

$$
\mathbb{P} (\eta_n > c_{n,\alpha}) \leq \mathbb{P} \left( \| \sqrt{n} (TG_n - G_n) \|_{W_Y \times U_X} > c_{n,\alpha}^* \right) = \alpha + o(1),
$$

with equality under the l.f.c. Under the alternative $H_1$ it can be easily shown that $\eta_n$ diverges to infinity, and because $c_{n,\alpha}^* = O(1)$ a.s.,

$$
\mathbb{P} (\eta_n > c_{n,\alpha}^*) \to 1.
$$

This completes the proof of Theorem 1. □

**Proof of Theorem 2:** Applying a classical mean value theorem argument, uniformly in $u \in [0, 1]$,

$$
\tilde{C}_{m_\theta, n} (u) = \tilde{C}_{m_\theta, n} (u) + \tilde{C}_{m_{\theta_0}, n} (u)' (\theta_n - \theta_0),
$$

where $\theta_n$ is an intermediate point that satisfies $|\theta_n - \theta_0| \leq |\theta_n - \theta_0|$. Define the class of functions on $X_Z$

$$
\mathcal{H}_1 \equiv \{ z \to \tilde{m}_\theta (z)(u - F(x)) 1_{\{F(x) \leq u\}} : u \in [0, 1], F \in \mathcal{H}_B, \theta \in \Theta_0 \}.
$$

By Examples 19.7 and 19.11 in van der Vaart (1998) and by Problem 8 in van der Vaart and Wellner (1996, pg. 204), $\mathcal{H}_1$ is a Glivenko-Cantelli class under Assumption S. Thus, by Assumption E and the classical Glivenko-Cantelli theorem, uniformly in $u \in [0, 1]$,

$$
\tilde{C}_{m_{\theta_0}, n} (u) = \tilde{C}_{m_{\theta_0}} (u) + o_p(1).
$$
Next, define the class of functions

\[ \mathcal{H}_2 \equiv \{ z \mapsto q_{u,F}(z) \equiv m_{\theta_0}(z) (u - F(x)) 1_{\{F(x) \leq u\}} : u \in [0,1], F \in \mathcal{H}_B \}. \]

Note that for all \( u \in [0,1] \) and \( F \in \mathcal{H}_B \),

\[ E \left[ \sup |q_{u_1,F_1}(Z) - q_{u,F}(Z)|^2 \right] \leq K\delta^2, \]

where the supremum is over the set \( u_1 \in [0,1] \) and \( F_1 \in \mathcal{H}_B \) such that \( |u_1 - u| \leq \delta \) and \( \sup_{x \in \mathbb{R}} |F_1(x) - F(x)| \leq \delta \), respectively. By Lemma A1 and Theorem 19.5 in van der Vaart (1998), the class \( \mathcal{H}_2 \) is \( P \)-Donsker. Hence, by the classical Glivenko-Cantelli theorem

\[ \sup_{u \in [0,1]} |G_{Zn}q_{u,F_{Xn}} - G_{Zn}q_{u,F_X}| \to_p 0. \]

Furthermore, since under the l.f.c \( Pq = 0 \), for all \( q \in \mathcal{H}_2 \),

\[ \sup_{u \in [0,1]} \left| \tilde{C}_{m_{\theta_0},n}(u) - \tilde{C}_{m_{\theta_0},n}(u) \right| = o_p \left( n^{-1/2} \right), \tag{20} \]

where \( \tilde{C}_{m_{\theta_0},n} \) is defined as \( \bar{C}_{m_{\theta_0},n} \) but with \( F_{Xn} \) replaced by the true cdf \( F_X \). Then, (18), (19) and (20) yield (9) under the l.f.c.

We now prove the validity of the bootstrap approximation. Using the mean value theorem, we write

\[ \frac{1}{n} \sum_{i=1}^{n} m_{\theta_n}(Z_i) (u - F_{Xn}(X_i)) 1_{\{F_{Xn}(X_i) \leq u\}} V_i \]

\[ = \frac{1}{n} \sum_{i=1}^{n} m_{\theta_0}(Z_i) (u - F_{Xn}(X_i)) 1_{\{F_{Xn}(X_i) \leq u\}} V_i \]

\[ + (\theta_n - \theta_0) \frac{1}{n} \sum_{i=1}^{n} \tilde{m}_{\theta_n}(Z_i) (u - F_{Xn}(X_i)) 1_{\{F_{Xn}(X_i) \leq u\}} V_i \]

\[ \equiv I_{1n}(u) + I_{2n}(u), \tag{21} \]

where \( \theta_n \) is an intermediate point that satisfies \( |\theta_n - \theta_0| \leq |\theta_n - \theta_0| \) a.s.

Noticing that the class of real-valued measurable functions on \( \mathcal{X}_Z \times \mathcal{X}_V \)

\[ \mathcal{H}_{1,*} \equiv \{ (z,v) \mapsto \tilde{m}_{\theta}(z) (u - F(x)) 1_{\{F(x) \leq u\}} v : u \in [0,1], F \in \mathcal{H}_B, \theta \in \Theta_0 \}, \]
Thus, the rest of the proof follows the reasoning of Theorem 1 in a routine fashion.

On the other hand, by Assumption E and a strong uniform law of large numbers,

$$\text{Var}^* \left( \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \{1_{\theta_n}(Z_i, X_i) - 1_{\theta_0}(Z_i, X_i)\} V_i \right)$$

$$= \frac{1}{n} \sum_{i=1}^{n} (1_{\theta_n}(Z_i, X_i) - 1_{\theta_0}(Z_i, X_i))(1_{\theta_n}(Z_i, X_i) - 1_{\theta_0}(Z_i, X_i))'$$

$$= o(1), \text{ a.s.}$$

Thus,

$$\frac{1}{\sqrt{n}} \sum_{i=1}^{n} 1_{\theta_n}(Z_i, X_i)V_i = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} 1_{\theta_0}(Z_i, X_i)V_i + o_{\text{pp}}(1), \text{ a.s.}$$

(23)

The expansions (21), (22) and (23), and the multiplier central limit theorem, see Theorem 2.9.2 in van der Vaart and Wellner (1996), imply that $\tilde{C}_{m_{\theta_n}, n}$ converges weakly (almost surely) to the same weak limit as $\tilde{C}_{m_{\theta_n}, n}$ in $(\ell^\infty(U_X), \| \cdot \|_{U_X})$. From this point, the rest of the proof follows the reasoning of Theorem 1 in a routine fashion.

Details are omitted. □

**Proof of Theorem 3:** The proof follows the same steps as that of Theorem 1. Hence, to save space we only discuss here the differences. Let $\hat{F}_{X_n}$ denote the empirical cdf of $\{\beta'_n X_i\}_{i=1}^{n}$ and let $\hat{C}_n$ be defined as $\tilde{C}_n$ but with $\hat{F}_{X_n}$ replacing the true cdf $F_{\beta' X}$. Set $\hat{\Delta}_n \equiv \sqrt{n} \left( T \hat{C}_n - \hat{C}_n \right)$. Define the class of functions

$$\mathcal{G}_3 \equiv \{ \bar{x} \in X \rightarrow f_{u,F,\beta}(\bar{x}) \equiv (u - F(\beta' \bar{x}))1_{\{F(\beta' \bar{x}) \leq u\}} : u \in [0, 1], \ F \in \mathcal{L}_B, \ \beta \in \Theta \},$$

where $\mathcal{L}_B$ is the set of Lipschitz functions in $\mathcal{H}_B$, i.e, for all $z_1$ and $z$ in $\mathbb{R}$, with $z_1 \geq z$,

$$F(z_1) - F(z) \leq K[z_1 - z].$$

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We prove that \( G_3 \) is \( P_Z \)-Donsker. To that end, note that for each \((u,F) \in [0,1] \times \mathcal{H}_B\), using the triangle inequality and the simple inequality \( |a_+ - b_+|^2 \leq |a - b|^2 \) for all \( a, b \in \mathbb{R} \), where \( a_+ = \max\{a, 0\} \), we obtain
\[
\mathbb{E} \left[ \sup |f_{u_1,F_1,\beta_1}(X) - f_{u,F,\beta}(X)|^2 \right] \leq 2 \mathbb{E} \left[ \sup |F_1(\beta'_1 X) - F_2(\beta'_1 X)|^2 \right] + 2 \mathbb{E} \left[ \sup |F_2(\beta'_1 X) - F_2(\beta'_2 X)|^2 \right] \leq K (1 + \mathbb{E} [|X|^2]) \delta^2,
\]
where the supremum is over the set \( u_1 \in [0,1], F_1 \in \mathcal{L}_B \) and \( \beta_1 \in \Theta \) such that \(|u_1 - u| \leq \delta, \sup_x \mathbb{E} |F_1(x) - F(x)| \leq \delta \) and \(|\beta_1 - \beta| \leq \delta\), respectively. By Lemma A1, the class \( G_3 \), and hence \( \mathcal{H} \equiv G_1 \cdot G_3 \), is \( P_Z \)-Donsker.

We now prove that \( \mathbb{P} \left( \hat{F}_{X_n} \in \mathcal{L}_B \right) \to 1 \) as \( n \to \infty \). First, notice that \( \hat{F}_{X_n} \in \mathcal{H}_B \) for each \( n \geq 1 \). Also, by Chebyshev inequality, for all \( z_1 \geq z \) and any constant \( K_1 > 0 \),
\[
\mathbb{P} \left( \hat{F}_{X_n}(z_1) - \hat{F}_{X_n}(z) > K_1[\hat{z}_1 - \hat{z}] \right) \leq K_1^{-1} \hat{z}_1 - \hat{z}]^{-1} \mathbb{E} \left[ \hat{F}_{X_n}(z_1) - \hat{F}_{X_n}(z) \right] \leq K_1^{-1} \hat{z}_1 - \hat{z}]^{-1} \mathbb{E} \left[ \hat{s}(z_1, z) \right],
\]
where \( \hat{s}(z_1, z) \equiv 1_{\{\beta_n \leq z_1\}} - 1_{\{\beta_n \leq z\}} \). By Assumption M, and defining \( \beta_n = (1, \theta'_n)' \),
\[
\mathbb{E} \left[ \hat{s}(z_1, z) \right] = \mathbb{E} \left[ 1_{\{z_1 - \theta'_n X_{-1} \leq z_1 \leq z - \theta'_n X_{-1}\}} \right] = \mathbb{E} \left[ F_{X_1 | X_{-1}} (z_1 - \theta'_n X_{-1}, X_{-1}) - F_{X_1 | X_{-1}} (z - \theta'_n X_{-1}, X_{-1}) \right] \leq K [\hat{z}_1 - \hat{z}].
\]
Choosing \( K_1 \) sufficiently large we obtained the desired result.

Similarly, it can be shown that \( \hat{F}_{X_n} \) is uniformly consistent for \( F_{\beta_n X} \), since the class \( \{1_{\{\beta \leq z\}} : z \in \mathbb{R}, \beta \in \Theta\} \) is Glivenko-Cantelli, the map \( \beta \in \Theta \to \mathbb{E} \left[ 1_{\{\beta \leq z\}} \right] \) is continuous under Assumption M and \( \beta_n \) is consistent for \( \beta_0 \).

Thus, by a stochastic equicontinuity argument and the Glivenko-Cantelli theorem
\[
\sup_{(y,u) \in \Pi} \left| \mathbb{G}_Z h_{y,u,F_{X_n},\beta_n} - \mathbb{G}_Z h_{y,u,F_{\beta_0 X},\beta_0} \right| \to_p 0,
\]
where \( h_{y,u,F,\beta}(\bar{z}) \equiv \{1_{\{\bar{y}_1 \leq y\}} - 1_{\{\bar{y}_2 \leq y\}}\} (u - F(\beta' \bar{x})) 1_{\{F(\beta' \bar{x}) \leq u\}} \). From the arguments of Theorem 1, we conclude that under the l.f.c.
\[
\sup_{(y,u) \in \mathcal{W}_Y \times \mathcal{U}_X} \hat{\Delta}_n(y,u) = \sup_{(y,u) \in \mathcal{W}_Y \times \mathcal{U}_X} \tilde{\Delta}_n(y,u) + o_p(1).
\]
From here, the same arguments of Theorem 1 lead to

\[ \hat{\eta}_n(\beta_n) = \hat{\eta}_n(\beta_0) + o_P(1), \]

under the l.f.c. □

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REFERENCES


### Table 1: Rejection probabilities

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1000 Bootstrap replications. 10000 Monte Carlo simulations.

### Table 2: Rejection probabilities. Index Model.

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1000 Bootstrap replications. 10000 Monte Carlo simulations.
Table 3: Nonparametric tests for the NSW. Bootstrap p-values.

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<td>0.634</td>
<td>0.515</td>
<td>0.404</td>
</tr>
</tbody>
</table>

10000 Bootstrap replications. Cross-validated bandwidth.
Figure 1: 5% Empirical power function for (12): Randomized experiment (Top panel) and Probit Model (Bottom panel). MC replications 10000. $B = 1000$.

Figure 2: Nonparametric kernel estimates of the conditional means of changes in earnings between 1978 and 1975, as a function of age.