

# The Unit Root Land

Material used and recommended:

- \* Hamilton (1994) "Time Series Analysis"  
chapters 15, 16, 17
- \* Fuller (1996) "Introduction to Statistical  
Time Series"  
chapter 10
- \* Billingsley (1999) "Convergence of  
Probability Measures"  
chapter 3
- \* Mikosch (2000) "Elementary Stochastic  
Calculus"  
chapters 1-2
- \* Phillips - "Lecture Notes"

# Reasons to study Unit root Models

$$X_t = X_{t-1} + \varepsilon_t \quad \varepsilon_t \sim \text{iid Random Walk}$$

$$X_t = \mu + X_{t-1} + \varepsilon_t \quad \varepsilon_t \sim \text{iid Random Walk with Drift}$$

## \* Growth

- \* The effect of a shock
- \* Trend-Cycle Decomposition
- \* Forecasting
- \* Asymptotic Results
- \* Testing for a Unit Root
  - Dickey - Fuller
  - Phillips - Perron
  - ...
- \* Problems of testing

## Growth:

$$- X_t = X_{t-1} + \varepsilon_t$$

$$- X_t = \mu + X_{t-1} + \varepsilon_t \rightarrow \Delta X_t = \mu + \varepsilon_t$$

$$X_t = \underline{\mu t} + \sum_{s=1}^t \varepsilon_s$$

$$- X_t = a + \underline{b t} + \varepsilon_t$$

## The effect of a shock:

$$\boxed{\frac{\partial X_{t+h}}{\partial \varepsilon_t}}$$

$$\text{Transitory shock: } h \rightarrow \infty \quad \frac{\partial X_{t+h}}{\partial \varepsilon_t} = 0$$

$$\text{Permanent shock: } h \rightarrow \infty \quad \frac{\partial X_{t+h}}{\partial \varepsilon_t} \neq 0$$

Examples: (1)  $X_t = \rho X_{t-1} + \varepsilon_t \quad |\rho| < 1$

$$X_t = \varepsilon_t + \rho \varepsilon_{t-1} + \rho^2 \varepsilon_{t-2} + \dots$$

$$X_{t+h} = \varepsilon_{t+h} + \rho \varepsilon_{t+h-1} + \rho^2 \varepsilon_{t+h-2} + \dots + \underline{\rho^h \varepsilon_t} + \dots$$

$$\frac{\partial X_{t+h}}{\partial \varepsilon_t} = \rho^h \rightarrow 0 \quad \text{as } h \rightarrow \infty$$

$$(2) \quad X_t = X_{t-1} + \varepsilon_t$$

$$X_t = \varepsilon_t + \varepsilon_{t-1} + \dots$$

$$X_{t+h} = \varepsilon_{t+h} + \varepsilon_{t+h-1} + \dots + \varepsilon_t + \dots$$

$$\lim_{h \rightarrow \infty} \frac{\partial X_{t+h}}{\partial \varepsilon_t} = 1 \neq 0$$

$$(3) \quad \Delta X_t = C(L)\varepsilon_t$$

$$= C(1)\varepsilon_t + (1-L)\tilde{C}(L)\varepsilon_t$$

$$X_t = C(1) \frac{\varepsilon_t}{1-L} + \tilde{C}(L)\varepsilon_t$$

$$X_{t+h} = C(1) \frac{\varepsilon_{t+h}}{1-L} + \tilde{C}(L)\varepsilon_{t+h}$$

$$\frac{\partial X_{t+h}}{\partial \varepsilon_t} = C(1) \neq 0 \quad \text{if } X_t \text{ has a unit root}$$

$$(4) \quad \text{Think on } X_t = a + bt + \varepsilon_t$$

where  $\varepsilon_t \equiv \psi(L) a_t$  stationary

# Trend-Cycle Decomposition

$$\Delta X_t = \mu + C(L) \varepsilon_t$$

$$\Delta X_t = \mu + C(1) \varepsilon_t + (1-L) \tilde{C}(L) \varepsilon_t$$

$$X_t = \mu t + C(1) \left( \frac{\varepsilon_t}{\Delta} \right) + \tilde{C}(L) \varepsilon_t$$

Deterministic  
Trend

Stochastic  
Trend

Cycle

or

Permanent  
Component

Transitory  
Component

Remember the conditions on the polynomial  $C(L)$  in order for  $\tilde{C}(L)$  to behave correctly (???)

# Forecasting

Comparison between an  $I(0)$  and an  $I(1)$

$$X_t = a + bt + C(L) \varepsilon_t \quad \text{Trend stationary}$$

$$\sum_{j=1}^{\infty} |c_j| < \infty$$

$$X_{t+h} = a + b(t+h) + \varepsilon_{t+h} + c_1 \varepsilon_{t+h-1} + \dots + c_h \varepsilon_t + \dots$$

$$E[X_{t+h} | I_t] = a + b(t+h) + c_h \varepsilon_t + c_{h+1} \varepsilon_{t-1} + \dots$$

$$E[X_{t+h} - E[X_{t+h} | I_t]]^2 \rightarrow \text{constant as } h \rightarrow \infty$$

Now

$$X_t = \mu + X_{t-1} + C(L) \varepsilon_t \quad \text{Difference stationary}$$

$$X_{t+h} = h\mu + X_t + \varepsilon_{t+h} + (1+c_1)\varepsilon_{t+h-1} + \dots + (1+c_1+\dots+c_{h-1})\varepsilon_{t+1} + \dots$$

$$E[X_{t+h} | I_t] = h\mu + X_t + [1+c_1+\dots+c_h]\varepsilon_t + [\dots]\varepsilon_{t-1}$$

$$E[X_{t+h} - E[X_{t+h} | I_t]]^2 \rightarrow \infty \text{ as } h \rightarrow \infty$$

# Asymptotic Results

$$X_t = \rho X_{t-1} + \varepsilon_t \quad \varepsilon_t \sim N(0, \sigma^2) \\ \text{iid}$$

IF  $|\rho| < 1$

$$\sqrt{T} (\hat{\rho}_T - \rho) \sim N(0, 1 - \rho^2)$$

$$\sqrt{T} (\hat{\rho}_T - 1) \xrightarrow{P} 0$$

IF  $\rho = 1$

$$(\hat{\rho}_T - 1) = \frac{\sum_{t=1}^T X_{t-1} \varepsilon_t}{\sum_{t=1}^T X_{t-1}^2}$$

$$\frac{1}{T} \sum_{t=1}^T X_{t-1} \varepsilon_t$$

$$X_t^2 = (X_{t-1} + \varepsilon_t)^2 = X_{t-1}^2 + 2X_{t-1}\varepsilon_t + \varepsilon_t^2$$

$$X_{t-1}\varepsilon_t = \frac{1}{2} \{ X_t^2 - X_{t-1}^2 - \varepsilon_t^2 \}$$

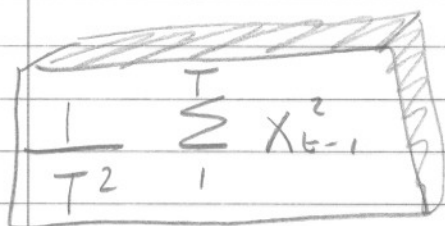
$$\sum_{t=1}^T X_{t-1}\varepsilon_t = \frac{1}{2} \{ X_T^2 - X_0^2 \} - \frac{1}{2} \sum_{t=1}^T \varepsilon_t^2$$

$$\frac{1}{T} \sum_{t=1}^T X_{t-1}\varepsilon_t = \frac{1}{2} \left( \frac{X_T^2}{T} \right) - \frac{1}{2} \left( \frac{\sum_{t=1}^T \varepsilon_t^2}{T} \right)$$

$\xrightarrow{d} \chi^2(1)$        $\xrightarrow{d} \sigma^2$

$$\frac{X_T}{\sigma\sqrt{T}} \xrightarrow{d} N(0, 1)$$

So  $\frac{1}{\sigma^2} \frac{1}{T} \sum_{t=1}^T X_{t-1} \varepsilon_t \stackrel{d}{\rightarrow} \frac{1}{2} (\chi_{(1)}^2 - 1)$



$$\frac{1}{T^2} \sum_{t=1}^T X_{t-1}^2$$

$$X_{t-1} \sim N(0, \sigma^2(t-1))$$

$$E\left(\sum_{t=1}^T X_{t-1}^2\right) = E\left\{\sum_{t=1}^{T-1} \left(\sum_{i=1}^t \varepsilon_i\right)^2\right\}$$

$$= \frac{1}{2} T(T-1) \sigma^2$$

$$V\left(\sum_{t=1}^T X_{t-1}^2\right) = \frac{1}{3} T(T-1)(T^2 - T + 1) \sigma^4$$

$$\frac{\sum_{t=1}^T X_{t-1}^2}{\frac{1}{2} T(T-1) \sigma^2} \begin{cases} E[\ ] = 1 \\ V[\ ] = \frac{4(T^2 - T + 1)}{3(T^2 - T)} \xrightarrow{T \rightarrow \infty} \frac{4}{3} \end{cases}$$

So  $\frac{1}{T^2} \sum_{t=1}^T X_{t-1}^2$  doesn't converge to a constant in mean square.

[Notice the difference with  
the case  $\rho=1$ ]

## Brownian Motion

Def:  $B$  is a stochastic process  $\{B(t) : 0 \leq t < \infty\}$  on a probability space  $(\Omega, \mathcal{F}, P)$  with properties:

(a)  $B(0, \omega) = 0 \quad \forall \omega$

(b)  $B(\cdot, \omega) = 0$  is continuous for each  $\omega$

(c) For  $0 < t_1 < t_2 < \dots < t_{n-1} < t_n$ , the incrementes  $B(t_1), B(t_2) - B(t_1), \dots, B(t_n) - B(t_{n-1})$  are independent and normally distributed, with means 0 and variances  $t_1, t_2 - t_1, \dots, t_n - t_{n-1}$ .

Def : A Brownian motion is a gaussian process with  $E(B(t)) = 0$  and  $\text{Cov}(B(s), B(t)) = s \wedge t$

[For a graphizal view see the Applet on my web page]

# Construction of a Brownian motion

Let  $\{u_t\}_{t=0}^{\infty}$  be a stochastic process

such that:

- (1)  $E(u_t) = 0$  for all  $t$
- (2)  $\sup E|u_t|^\beta < \infty$  for some  $\beta > 2$
- (3)  $\sigma^2 = \lim_{t \rightarrow \infty} \frac{1}{t} E[S_t^2]$  exists and  $\sigma^2 > 0$ ;

$S_T = \sum_{i=1}^T u_i$  and  $\sigma^2$  can also be

Written as  $\boxed{\sigma^2 = \sigma_u^2 + 2\lambda}$  with  
 $\sigma_u^2 = E(u_i^2)$  and  $\lambda = \sum_{j=2}^{\infty} E(u_i u_j)$

- (4)  $u_t$  is strongly-mixing with mixing coefficients  $\alpha_m$  such that  $\sum_1^{\infty} \alpha_m^{(1-\frac{2}{p})} < \infty$ .

Let's consider  $X_T = \frac{1}{\sqrt{T}} S_T = \frac{1}{\sqrt{T}} \sum_{i=1}^T u_i$

Notice that

$$\frac{1}{\sqrt{T}} S_T \Rightarrow N(0, \sigma^2)$$

$$\frac{1}{\sqrt{[T/2]}} \sum_{i=1}^{[T/2]} u_i \Rightarrow N(0, \sigma^2)$$

where  $[T/2]$  denotes the largest integer that is less or equal to  $T/2$ .

Now consider the following variable (process)

$$X_T(r) = \frac{1}{\sqrt{T}} \sum_{k=1}^{[Tr]} u_k \quad r \in [0,1]$$

For any given realization,  $X_T(r)$  is a step function in  $r$ , with

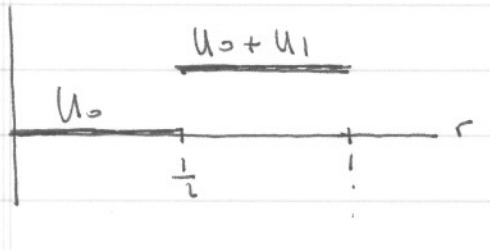
$$\begin{aligned} X_T(r) &= 0 & \text{for } 0 \leq r < \frac{1}{T} \\ &= (u_1)/\sqrt{T} & \text{for } \frac{1}{T} \leq r < \frac{2}{T} \\ &= (u_1 + u_2)/\sqrt{T} & \text{for } \frac{2}{T} \leq r < \frac{3}{T} \\ &\vdots & \vdots \\ &= (u_1 + u_2 + \dots + u_T)/\sqrt{T} & \text{for } r = 1 \end{aligned}$$

T=1



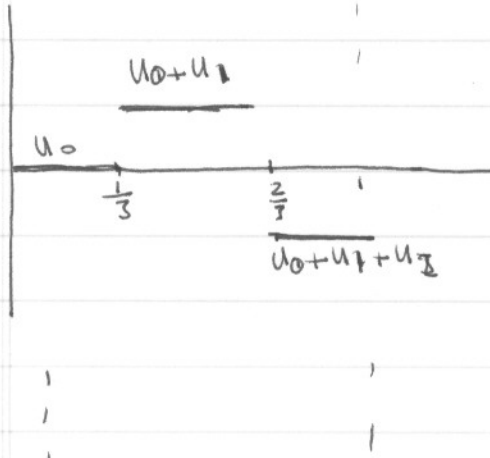
$$X_1(r) = \frac{1}{\sqrt{1}} \sum_{k=1}^{[1r]} u_k = \frac{1}{\sqrt{1}} u_0 = 0$$

T=2



$$X_2(r) = \frac{1}{\sqrt{2}} \sum_{k=1}^{[2r]} u_k = \begin{cases} \frac{1}{\sqrt{2}} u_0 & 0 \leq r < \frac{1}{2} \\ \frac{1}{\sqrt{2}} (u_0 + u_1) & \frac{1}{2} \leq r < 1 \end{cases}$$

T=3



$$X_3(r) = \frac{1}{\sqrt{3}} \sum_{k=1}^{[3r]} u_k = \begin{cases} \frac{1}{\sqrt{3}} u_0 & 0 \leq r < \frac{1}{3} \\ \frac{1}{\sqrt{3}} (u_0 + u_1) & \frac{1}{3} \leq r < \frac{2}{3} \\ \frac{1}{\sqrt{3}} (u_0 + u_1 + u_2) & \frac{2}{3} \leq r < 1 \end{cases}$$

Then 
$$X_T(r) = \frac{1}{\sqrt{T}} \sum_{t=1}^{[Tr]} u_t$$

$$= \left( \sqrt{[Tr]} / \sqrt{T} \right) \left( \frac{1}{\sqrt{[Tr]}} \right) \sum_{t=1}^{[Tr]} u_t$$

But 
$$\left( \frac{1}{\sqrt{[Tr]}} \right) \sum_{t=1}^{[Tr]} u_t \Rightarrow N(0, \sigma^2) \quad \text{by the CLT}$$

$$\sqrt{[Tr]} / \sqrt{T} \rightarrow \sqrt{r}$$

Therefore 
$$X_T(r) \Rightarrow N(0, r\sigma^2)$$

and

$$\boxed{\frac{X_T(r)}{\sigma} \Rightarrow N(0, r)}$$

In similar way ( $r_2 > r_1$ )

$$\boxed{(X_T(r_2) - X_T(r_1)) / \sigma \Rightarrow N(0, r_2 - r_1)}$$

The sequence of stochastic functions,

$\left\{ X_T(\cdot) / \sigma \right\}_{T=1}^{\infty}$  has an asymptotic

probability law that is described

by the Wiener process  $W(\cdot)$

$$\boxed{X_T(\cdot) / \sigma \xRightarrow{L} W(\cdot)}$$

or

$$\boxed{X_T(\cdot) \Rightarrow \sigma^2 W(\cdot)}$$

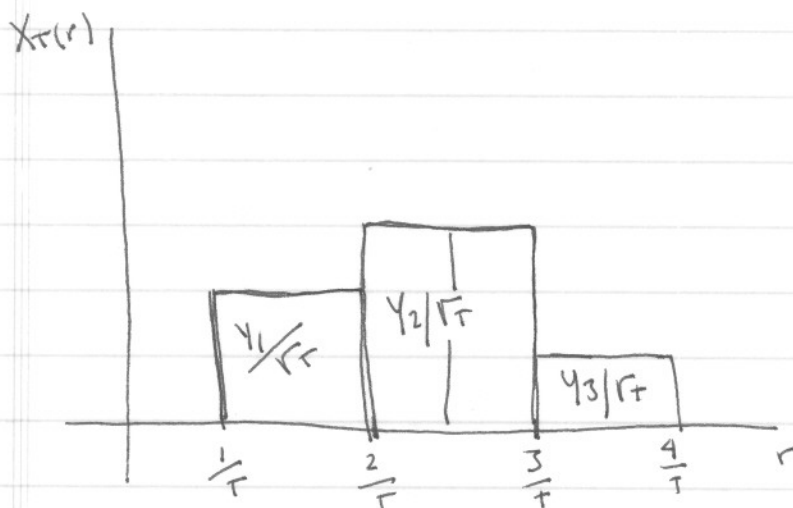
Functional Central  
Limit Theorem (see Appendix)

# Application to Unit root processes

$$Y_t = Y_{t-1} + u_t$$

$$Y_t = u_1 + u_2 + \dots + u_t$$

$$\begin{aligned} X_T(r) &= 0 & \text{for } 0 \leq r < 1/T \\ &= Y_1/\sqrt{T} & \text{for } 1/T \leq r < 2/T \\ &= Y_2/\sqrt{T} & \text{for } 2/T \leq r < 3/T \\ &\vdots \\ &= Y_T/\sqrt{T} & \text{for } r = 1 \end{aligned}$$



$$\begin{aligned} \int_0^1 X_T(r) dr &= Y_1/T^{3/2} + Y_2/T^{3/2} + \dots + Y_{T-1}/T^{3/2} \\ &= T^{-3/2} \sum_{t=1}^T Y_{t-1} \end{aligned}$$

$$\Rightarrow \sigma \int_0^1 W(r) dr$$

By the Continuous mapping theorem

$$T^{-3/2} \sum_{k=1}^T Y_{t_{k-1}} \Rightarrow \underbrace{\sigma^2 \int_0^1 W(r) dr}_{\text{Integrated Brownian Motion}}$$

Integrated Brownian Motion

Some Properties:

$$E \left[ \int_0^t W(s) ds \right] = \int_0^t E(W(s)) ds = \underline{\underline{0}}$$

$$\begin{aligned} s \leq t \quad \text{Cov} \left[ \int_0^s W(y) dy, \int_0^t W(u) du \right] &= \\ &= E \left[ \int_0^s \int_0^t W(y) W(u) dy du \right] \\ &= \int_0^s \int_0^t E[W(y) W(u)] dy du \\ &= \int_0^s \int_0^t \min(y, u) dy du \\ &= \int_0^s \left( \int_0^u y dy + \int_u^t u dy \right) du \\ &= s^2 \left( \frac{t}{2} - \frac{s}{2} \right) \end{aligned}$$

$$\text{If } t=s=1 \text{ then } \text{Cov}(\ ) = \frac{1}{3}$$

$$\text{So } \underline{\underline{\int_0^1 W(r) dr \equiv N(0, \frac{1}{3})}}$$

## Other averages

$$\begin{aligned}
 T^{-3/2} \sum_{t=1}^T Y_{t-1} &= T^{-3/2} [u_1 + (u_1 + u_2) + (u_1 + u_2 + u_3) + \dots + (u_1 + u_2 + \dots + u_{T-1})] \\
 &= T^{-3/2} [(T-1)u_1 + (T-2)u_2 + (T-3)u_3 + \dots + [T-(T-1)]u_{T-1}] \\
 &= T^{-3/2} \sum_{t=1}^T (T-t) u_t \\
 &= T^{-1/2} \sum_{t=1}^T u_t - T^{-3/2} \sum_{t=1}^T t u_t
 \end{aligned}$$

Therefore

$$\begin{aligned}
 T^{-3/2} \sum_{t=1}^T t u_t &= T^{-1/2} \sum_{t=1}^T u_t - T^{-3/2} \sum_{t=1}^T Y_{t-1} \\
 &\Rightarrow \sigma W(1) - \sigma \int_0^1 W(r) dr \equiv N(0, \sigma^2/3)
 \end{aligned}$$

$$\text{Cov} \left( \int_0^t W(r) dr, W(t) \right) = \frac{t^2}{2}$$

$$\sum_{k=1}^T Y_{k-1}^2$$

Define  $S_T(r) = [X_T(r)]^2$ ;

$$\begin{aligned} S_T(r) &= 0 & \text{for } 0 \leq r < 1/T \\ &= Y_1^2/T & \text{for } 1/T \leq r < 2/T \\ &= Y_2^2/T & \text{for } 2/T \leq r < 3/T \\ &\vdots \\ &= Y_T^2/T & \text{for } r=1 \end{aligned}$$

It follows that

$$\begin{aligned} \int_0^1 (X_T(r))^2 dr &= \frac{Y_1^2}{T^2} + \frac{Y_2^2}{T^2} + \dots + \frac{Y_{T-1}^2}{T^2} \\ &\Rightarrow \sigma^2 \int_0^1 (W(r))^2 dr \end{aligned}$$

So

$$T^{-2} \sum_{k=1}^T Y_{k-1}^2 \Rightarrow \sigma^2 \int_0^1 (W(r))^2 dr$$

Other useful results:

$$T^{-\frac{5}{2}} \sum_{k=1}^T k Y_{k-1} = T^{-\frac{3}{2}} \sum_{k=1}^T \underbrace{(k/T)}_{\frac{1}{T}} Y_{k-1} \Rightarrow \sigma \int_0^1 r W(r) dr$$

$$T^{-3} \sum_{k=1}^T k^2 Y_{k-1} = T^{-2} \sum_{k=1}^T (k/T) Y_{k-1}^2 \Rightarrow \sigma^2 \int_0^1 r (W(r))^2 dr$$

$$T^{-1} \sum_{t=1}^T y_{t-1} u_t \stackrel{(*)}{=} \left(\frac{1}{2}\right) \left(\frac{1}{T}\right) y_T^2 - \left(\frac{1}{2}\right) \left(\frac{1}{T}\right) (u_1^2 + u_2^2 + \dots + u_T^2)$$

$$= \frac{1}{2} \underbrace{x_T^2(1)}_{\Downarrow \sigma^2 [W(1)]^2} - \left(\frac{1}{2}\right) \left(\frac{1}{T}\right) \underbrace{(u_1^2 + u_2^2 + \dots + u_T^2)}_{\substack{\downarrow LLN \\ \sigma^2}}$$

Therefore

$$\boxed{\frac{1}{T} \sum_{t=1}^T y_{t-1} u_t \Rightarrow \frac{1}{2} \sigma^2 [W(1)^2 - 1]}$$

$$(*) \quad \frac{1}{T} \sum_{t=1}^T y_{t-1} u_t = \left(\frac{1}{T}\right) \left\{ (u_1)(u_2) + (u_1 + u_2)u_3 + (u_1 + u_2 + u_3)u_4 + \dots + (u_1 + u_2 + u_3 + \dots + u_{T-1})u_T \right\}$$

Notice that

$$\begin{aligned} \left(\frac{1}{T}\right) y_T^2 &= \left(\frac{1}{T}\right) (u_1 + u_2 + \dots + u_T)^2 \\ &= \left(\frac{1}{T}\right) \left\{ (u_1^2 + u_2^2 + \dots + u_T^2) + 2(u_1 u_2) + 2(u_1 u_3) + \dots + 2(u_1 u_T) \right. \\ &\quad \left. + 2(u_2 u_3) + 2(u_2 u_4) + \dots + 2(u_{T-1} u_T) \right\} \end{aligned}$$

Therefore

$$\left(\frac{1}{T}\right) y_T^2 = \frac{1}{T} (u_1^2 + u_2^2 + \dots + u_T^2) + 2 \left(\frac{1}{T}\right) \sum_{t=1}^T y_{t-1} u_t$$

$$\frac{y_T, N(0,1)}{T}$$

# Summary of important results

$$\boxed{X_t = X_{t-1} + u_t} \quad \text{where } u_t \sim \text{iid} \quad E(u_t) = 0 \quad V(u_t) = \sigma^2$$

(a)  $T^{-1/2} \sum_{t=1}^T u_t \Rightarrow \sigma W(1)$

(\*) (b)  $T^{-1} \sum_{t=1}^T X_{t-1} u_t \Rightarrow \frac{1}{2} \sigma^2 \{ [W(1)]^2 - 1 \} = \boxed{\int_0^1 W dW}$

(c)  $T^{-3/2} \sum_{t=1}^T t u_t \Rightarrow \sigma W(1) - \sigma \int_0^1 W(r) dr \equiv N(0, \sigma^2/3)$

(d)  $T^{-3/2} \sum_{t=1}^T X_{t-1} \Rightarrow \sigma \int_0^1 W(r) dr$

(e)  $T^{-2} \sum_{t=1}^T X_{t-1}^2 \Rightarrow \sigma^2 \int_0^1 (W(r))^2 dr$

(f)  $T^{-5/2} \sum_{t=1}^T t X_{t-1} \Rightarrow \sigma \int_0^1 r W(r) dr$

(g)  $T^{-3} \sum_{t=1}^T t X_{t-1}^2 \Rightarrow \sigma^2 \int_0^1 r (W(r))^2 dr$

(h)  $T^{-(v+1)} \sum_{t=1}^T t^v \xrightarrow{P} 1/v+1 \quad \text{for } v = 0, 1, \dots$

# DICKEY-FULLER TESTS for UNIT ROOT

Case (a)      DGP       $X_t = X_{t-1} + u_t$

Regression       $X_t = \rho X_{t-1} + u_t$        $\boxed{t_{\hat{\rho}}}$

Case (b)      DGP       $X_t = X_{t-1} + u_t$

Regression       $X_t = \alpha + \rho X_{t-1} + u_t$        $\boxed{t_{\hat{\rho}}}$

Case (b')      DGP       $X_t = \alpha + X_{t-1} + u_t$

Regression       $X_t = \alpha + \rho X_{t-1} + u_t$        $\boxed{t_{\hat{\rho}}}$

Case (c)      DGP       $X_t = X_{t-1} + u_t$

Regression       $X_t = \alpha + bt + \rho X_{t-1} + u_t$        $\boxed{t_{\hat{\rho}}}$

Case (c')      DGP       $X_t = \alpha + X_{t-1} + u_t$

Regression       $X_t = \alpha + bt + \rho X_{t-1} + u_t$        $\boxed{t_{\hat{\rho}}}$

Source: Fuller (1976)

# Unit Root Dist<sup>n</sup> Tables

$$T(\hat{\alpha}-1)$$

8.5

NONSTATIONARY TIME SERIES

371

Table 8.5.1. Empirical cumulative distribution of  $n(\hat{\rho}-1)$  for  $\rho=1$

| Sample Size<br>$n$ | Probability of a Smaller Value |       |       |       |       |       |       |       |
|--------------------|--------------------------------|-------|-------|-------|-------|-------|-------|-------|
|                    | 0.01                           | 0.025 | 0.05  | 0.10  | 0.90  | 0.95  | 0.975 | 0.99  |
| $\hat{\rho}$       |                                |       |       |       |       |       |       |       |
| 25                 | -11.9                          | -9.3  | -7.3  | -5.3  | 1.01  | 1.40  | 1.79  | 2.28  |
| 50                 | -12.9                          | -9.9  | -7.7  | -5.5  | 0.97  | 1.35  | 1.70  | 2.16  |
| 100                | -13.3                          | -10.2 | -7.9  | -5.6  | 0.95  | 1.31  | 1.65  | 2.09  |
| 250                | -13.6                          | -10.3 | -8.0  | -5.7  | 0.93  | 1.28  | 1.62  | 2.04  |
| 500                | -13.7                          | -10.4 | -8.0  | -5.7  | 0.93  | 1.28  | 1.61  | 2.04  |
| $\infty$           | -13.8                          | -10.5 | -8.1  | -5.7  | 0.93  | 1.28  | 1.60  | 2.03  |
| $\hat{\rho}_p$     |                                |       |       |       |       |       |       |       |
| 25                 | -17.2                          | -14.6 | -12.5 | -10.2 | -0.76 | 0.01  | 0.65  | 1.40  |
| 50                 | -18.9                          | -15.7 | -13.3 | -10.7 | -0.81 | -0.07 | 0.53  | 1.22  |
| 100                | -19.8                          | -16.3 | -13.7 | -11.0 | -0.83 | -0.10 | 0.47  | 1.14  |
| 250                | -20.3                          | -16.6 | -14.0 | -11.2 | -0.84 | -0.12 | 0.43  | 1.09  |
| 500                | -20.5                          | -16.8 | -14.0 | -11.2 | -0.84 | -0.13 | 0.42  | 1.06  |
| $\infty$           | -20.7                          | -16.9 | -14.1 | -11.3 | -0.85 | -0.13 | 0.41  | 1.04  |
| $\hat{\rho}_t$     |                                |       |       |       |       |       |       |       |
| 25                 | -22.5                          | -19.9 | -17.9 | -15.6 | -3.66 | -2.51 | -1.53 | -0.43 |
| 50                 | -25.7                          | -22.4 | -19.8 | -16.8 | -3.71 | -2.60 | -1.66 | -0.65 |
| 100                | -27.4                          | -23.6 | -20.7 | -17.5 | -3.74 | -2.62 | -1.73 | -0.75 |
| 250                | -28.4                          | -24.4 | -21.3 | -18.0 | -3.75 | -2.64 | -1.78 | -0.82 |
| 500                | -28.9                          | -24.8 | -21.5 | -18.1 | -3.76 | -2.65 | -1.78 | -0.84 |
| $\infty$           | -29.5                          | -25.1 | -21.8 | -18.3 | -3.77 | -2.66 | -1.79 | -0.87 |

NOTE. This table was constructed by David A. Dickey using the Monte Carlo method. Details are given in Dickey (1975). Standard errors of the estimates vary, but most are less than 0.15 for entries in the left half of the table and less than 0.03 for entries in the right half of the table.

Although the sign of  $e_{t-j}$  in the weighted sum  $\sum_{j=0}^{t-1} (-1)^j e_{t-j}$  is not the same

for all  $t$ , the sign is always opposite of that for  $e_{t-j-1}$  and  $e_{t-j+1}$ , and it follows that

$$\sum_{t=1}^{n-1} X_t^2 = \sum_{t=1}^{n-1} \left( \sum_{j=1}^t (-1)^j e_j \right)^2$$

The distribution of  $e_t, t=1, 2, \dots$ , is symmetric and hence the distributional properties of the sequence  $-e_1, e_2, -e_3, e_4, \dots$ , are precisely the same as the

8.5

NONSTATIONARY TIME SERIES

373

Table 8.5.2. Empirical cumulative distribution of  $\hat{\tau}$  for  $\rho=1$

| Sample Size<br>$n$                                   | Probability of a Smaller Value |       |       |       |       |       |       |       |
|------------------------------------------------------|--------------------------------|-------|-------|-------|-------|-------|-------|-------|
|                                                      | 0.01                           | 0.025 | 0.05  | 0.10  | 0.90  | 0.95  | 0.975 | 0.99  |
| $\hat{\tau}$ Random walk                             |                                |       |       |       |       |       |       |       |
| 25                                                   | -2.66                          | -2.26 | -1.95 | -1.60 | 0.92  | 1.33  | 1.70  | 2.16  |
| 50                                                   | -2.62                          | -2.25 | -1.95 | -1.61 | 0.91  | 1.31  | 1.66  | 2.08  |
| 100                                                  | -2.60                          | -2.24 | -1.95 | -1.61 | 0.90  | 1.29  | 1.64  | 2.03  |
| 250                                                  | -2.58                          | -2.23 | -1.95 | -1.62 | 0.89  | 1.29  | 1.61  | 2.01  |
| 500                                                  | -2.58                          | -2.23 | -1.95 | -1.62 | 0.89  | 1.28  | 1.62  | 2.00  |
| $\infty$                                             | -2.58                          | -2.23 | -1.95 | -1.62 | 0.89  | 1.28  | 1.62  | 2.00  |
| $\hat{\tau}_p$ Random walk range                     |                                |       |       |       |       |       |       |       |
| 25                                                   | -3.75                          | -3.33 | -3.00 | -2.63 | -0.37 | 0.00  | 0.34  | 0.72  |
| 50                                                   | -3.58                          | -3.22 | -2.93 | -2.60 | -0.40 | -0.03 | 0.29  | 0.66  |
| 100                                                  | -3.51                          | -3.17 | -2.89 | -2.58 | -0.42 | -0.05 | 0.26  | 0.63  |
| 250                                                  | -3.46                          | -3.14 | -2.88 | -2.57 | -0.42 | -0.06 | 0.24  | 0.62  |
| 500                                                  | -3.44                          | -3.13 | -2.87 | -2.57 | -0.43 | -0.07 | 0.24  | 0.61  |
| $\infty$                                             | -3.43                          | -3.12 | -2.86 | -2.57 | -0.44 | -0.07 | 0.23  | 0.60  |
| $\hat{\tau}_t$ Random walk with drift and time trend |                                |       |       |       |       |       |       |       |
| 25                                                   | -4.38                          | -3.95 | -3.60 | -3.24 | -1.14 | -0.80 | -0.50 | -0.15 |
| 50                                                   | -4.15                          | -3.80 | -3.50 | -3.18 | -1.19 | -0.87 | -0.58 | -0.24 |
| 100                                                  | -4.04                          | -3.73 | -3.45 | -3.15 | -1.22 | -0.90 | -0.62 | -0.28 |
| 250                                                  | -3.99                          | -3.69 | -3.43 | -3.13 | -1.23 | -0.92 | -0.64 | -0.31 |
| 500                                                  | -3.98                          | -3.68 | -3.42 | -3.13 | -1.24 | -0.93 | -0.65 | -0.32 |
| $\infty$                                             | -3.96                          | -3.66 | -3.41 | -3.12 | -1.25 | -0.94 | -0.66 | -0.33 |

This table was constructed by David A. Dickey using the Monte Carlo method. Details are given in Dickey (1975). Standard errors of the estimates vary, but most are less than 0.02.

To extend the results for the first order process with  $\rho=1$  to the  $p$ th order autoregressive process, we consider the time series

$$Y_t = \sum_{j=1}^p Z_j \quad t=1, 2, \dots, \quad (8.5.11)$$

where  $\{Z_t: t \in (0, \pm 1, \pm 2, \dots)\}$  is a  $(p-1)$  order autoregressive time series with the representation

$$Z_t + \sum_{i=2}^p a_i Z_{t-i+1} = e_t \quad (8.5.12)$$

Case (a) DGP:  $X_t = \rho X_{t-1} + u_t$  Random Walk

Regression:  $X_t = \rho X_{t-1} + u_t$   $u_t \sim iid$   $E(u_t) = 0$   
 $V(u_t) = \sigma^2$

$$\hat{\rho}_T = \frac{\sum_{t=1}^T X_{t-1} X_t}{\sum_{t=1}^T X_{t-1}^2} = \rho + \frac{\sum_{t=1}^T X_{t-1} u_t}{\sum_{t=1}^T X_{t-1}^2}$$

$$T(\hat{\rho}_T - \rho) = \frac{T^{-1} \sum_{t=1}^T X_{t-1} u_t}{T^{-2} \sum_{t=1}^T X_{t-1}^2}$$

We know

$$T^{-1} \sum X_{t-1} u_t \Rightarrow \frac{1}{2} \sigma^2 \{W(1)^2 - 1\}$$

$$T^{-2} \sum X_{t-1}^2 \Rightarrow \sigma^2 \int_0^1 (W(r))^2 dr$$

Therefore

$$T(\hat{\rho}_T - \rho) \Rightarrow \frac{\frac{1}{2} \{W(1)^2 - 1\}}{\int_0^1 (W(r))^2 dr}$$

$$\sqrt{T}(\hat{\rho}_T - \rho) \Rightarrow N(0, 1 - \rho^2) \quad \text{when } |\rho| < 1$$

The Dickey-Fuller statistic is

2013

$$\boxed{t_{\hat{\beta}}}$$

$$t_T = \frac{(\hat{\beta}_T - 1)}{\hat{\sigma}_{\hat{\beta}_T}} = \frac{(\hat{\beta}_T - 1)}{\left\{ S_T^2 / \sum_{t=1}^T X_{t-1}^2 \right\}^{1/2}} \quad \underline{\underline{\text{D-F test}}}$$

where  $S_T^2 = \frac{1}{T-1} \sum_{t=1}^T (X_t - \hat{\beta}_T X_{t-1})^2$

To find the A.D of  $t_T$  we need to rewrite  $t_T$  as:

$$t_T = T(\hat{\beta}_T - 1) \left\{ T^{-2} \sum_{t=1}^T X_{t-1}^2 \right\}^{1/2} \frac{1}{\{S_T^2\}^{1/2}}$$

$$= \frac{T^{-1} \sum_{t=1}^T X_{t-1} u_t}{\left\{ T^{-2} \sum_{t=1}^T X_{t-1}^2 \right\}^{1/2} \{S_T^2\}^{1/2}}$$

$$\Rightarrow \frac{\frac{1}{2} \sigma^2 \{ [W(1)]^2 - 1 \}}{\left\{ \sigma^2 \int_0^1 (W(r))^2 dr \right\}^{1/2} \{ \sigma^2 \}^{1/2}} =$$

$$\boxed{S_T^2 \xrightarrow{P} \sigma^2 \text{ by consistency of } \hat{\beta}_T}$$

$$\boxed{= \frac{1/2 \{ [W(1)]^2 - 1 \}}{\left\{ \int_0^1 W(r)^2 dr \right\}^{1/2}}}$$

D-F distribution

# OTHER THINGS TO KNOW

Case (b')

DGP:  $X_t = \alpha + X_{t-1} + u_t$

Regression  $X_t = a + \rho X_{t-1} + u_t$

$$X_t = X_0 + \alpha t + (u_1 + u_2 + \dots + u_t) \\ = X_0 + \alpha t + \xi_t$$

$$\sum_1^T X_{t-1} = \sum_1^T [X_0 + \alpha(t-1) + \xi_{t-1}]$$

$$\boxed{T^{-1}} \downarrow \\ \underline{\underline{X_0}}$$

$$\boxed{T^{-2}} \downarrow \\ \underline{\underline{\alpha/2}}$$

$$\boxed{T^{-3/2}} \downarrow \\ \underline{\underline{\sigma \int_0^1 W(r) dr}}$$

So we need to divide  $\sum_1^T X_{t-1}$  by  $\boxed{T^2}$

to get something that "makes sense"

$$\boxed{T^{-2} \sum_1^T X_{t-1} = T^{-1} X_0 + T^{-2} \sum_1^T \alpha(t-1) + T^{-1/2} \sum_1^T \xi_{t-1}}$$

$$\xrightarrow{p} 0 + \alpha/2 + 0 = \underline{\underline{\alpha/2}}$$

Similarly

$$\sum_1^T X_{t-1}^2 = \underbrace{\sum_1^T X_0^2}_{O_p(T)} + \underbrace{\sum_1^T \alpha'(t-1)^2}_{O_p(T^3)} + \underbrace{\sum_1^T \varepsilon_{t-1}^2}_{O_p(T^2)} + 2 \underbrace{\sum_1^T 2y_0 \alpha(t-1)}_{O_p(T^2)} + \underbrace{\sum_1^T 2y_0 \varepsilon_{t-1}}_{O_p(T^{3/2})} + \underbrace{\sum_1^T 2\alpha(t-1)\varepsilon_{t-1}}_{O_p(T^{5/2})}$$

So

$$\boxed{T^{-3} \sum_1^T X_{t-1}^2 \xrightarrow{P} \alpha^2/3}$$

Finally

$$\sum_1^T X_{t-1} u_t = X_0 \underbrace{\sum_1^T u_t}_{O_p(T^{1/2})} + \underbrace{\sum_1^T \alpha(t-1) u_t}_{O_p(T^{3/2})} + \underbrace{\sum_1^T \varepsilon_{t-1} u_t}_{O_p(T)}$$

So

$$\boxed{T^{-3/2} \sum_1^T X_{t-1} u_t \Rightarrow T^{-3/2} \sum_1^T \alpha(t-1) u_t}$$

Putting every piece together

$$\boxed{\begin{bmatrix} T^{1/2} (\hat{\alpha}_T - \alpha) \\ T^{3/2} (\hat{\beta}_T - 1) \end{bmatrix} \Rightarrow N \left[ 0, Q^{-1} \cdot \sigma^2 \right]}$$

where

$$Q = \begin{bmatrix} 1 & \alpha/2 \\ \alpha/2 & \alpha^2/3 \end{bmatrix}$$

So  $\hat{\alpha}_T$  ???

Case (c) and (c'): DGP  $X_t = \rho + X_{t-1} + u_t$

Regression  $X_t = a + b_t + \rho X_{t-1} + u_t$

$E\hat{\rho} \Rightarrow$  D.F distribution that  
DOES NOT DEPEND ON  $\alpha$  or  $\sigma$

Think on a strategy  
to test for unit roots.

# What if $u_t$ is correlated

$$X_t = X_{t-1} + u_t \quad \text{and} \quad u_t = \psi(L) e_t$$

with  $e_t \sim \underline{iid}$

NOTE:

$$(1) \quad X_t = \rho X_{t-1} + u_t \quad H_0: \rho = 1 \quad H_A: |\rho| \neq 1$$

$$\Delta X_t = (\rho - 1) X_{t-1} + u_t \quad H_0: (\rho - 1) = 0 \quad H_A: (\rho - 1) < 0$$

(2)

$$\psi(L)^{-1} = A(L) = A(1) + (1-L) A^*(L)$$

$$A(0) = 1$$

(3)

$$\Delta X_t = \rho X_{t-1} + \psi(L) e_t$$

(4)

$$\psi^{-1}(L) \Delta X_t = (\rho - 1) \psi^{-1}(L) X_{t-1} + e_t$$

or

$$\Delta X_t = (\rho - 1) A(1) X_{t-1} + (\rho - 1) \Delta A^*(L) X_{t-1}$$

$$+ (A(L) + A(0)) \Delta X_t + e_t$$

(5)

$$\Delta X_t = \alpha^* X_{t-1} + \text{LAGS of } \Delta X_t + e_t$$

(6)  $\boxed{t \hat{\alpha}^*}$  has the same AD as  $t \hat{\rho}$  in case (a)

## DF and deterministic terms

$$(1) \quad X_t = \rho X_{t-1} + u_t$$

$$X_t = a + \rho X_{t-1} + u_t$$

$$X_t = a + bt + \rho X_{t-1} + u_t$$

$$(2) \quad X_t = \left( \begin{array}{c} \text{polynomial} \\ \text{in } t \end{array} \right) + \rho X_{t-1} + u_t$$

Under the  $H_0$  of  $X_t = X_{t-1} + u_t$

$$t_T = \frac{(\hat{\beta}_T - 1)}{\hat{\sigma}_{\hat{\beta}_T}} \Rightarrow \frac{\int_0^1 W(r) dW(r)}{\left( \int_0^1 W(r)^2 dr \right)^{\frac{1}{2}}} \quad \text{in (1)}$$

In general (2)

$$t_T = \frac{(\hat{\beta}_T - 1)}{\hat{\sigma}_{\hat{\beta}_T}} \Rightarrow \frac{\int_0^1 W_D(r) dW(r)}{\left( \int_0^1 W_D(r)^2 dr \right)^{\frac{1}{2}}}$$

where

$$W_D(r) = W(r) - \left[ \int_0^1 W(r) D(r) dr \right] \left[ \int_0^1 D(r) D(r) dr \right]^{-1} D(r) \quad \text{is the}$$

Hilbert projection in  $L_2[0,1]$  of  $W$  onto the space orthogonal to  $D$ .  $D(r) = (1, r, \dots, r^p)'$

$$D(r) = (1, r, \dots, r^p)'$$

# Phillips - Perron tests ( $Z_\alpha$ and $Z_t$ )

$$X_t = \rho X_{t-1} + u_t \quad \text{with} \quad u_t = C(L) \varepsilon_t$$

$$T(\hat{\rho} - 1) = \frac{\frac{1}{T} \sum_{t=1}^T X_{t-1} u_t}{\frac{1}{T^2} \sum_{t=1}^T X_{t-1}^2} \Rightarrow \frac{\left[ \int B(r) dB(r) + \lambda \right]}{\left[ \int B^2(r) dr \right]}$$

$$t_{\hat{\rho}} \Rightarrow \frac{(\hat{\rho}_T - 1)}{\left( \hat{\sigma}_u^2 / \sum_{t=1}^T X_{t-1}^2 \right)^{1/2}} \Rightarrow \frac{\int_0^1 B(r) dB(r) + \lambda}{\sigma_u \left[ \int_0^1 B^2(r) dr \right]^{1/2}}$$

where

$$\sigma_u^2 = V(u_t), \quad B(r) \text{ is a BM with variance } w^2 = \sigma_\varepsilon^2 C(1)^2$$

$$\text{and } \lambda = \sum_{j=1}^{\infty} E(u_0 u_j).$$

$$w^2 = \sigma_u^2 + 2\lambda$$

《THINK ON WHAT DOES IT HAPPEN IF  $u_t = \varepsilon_t$ ?》

$$Z_\alpha = T(\hat{\rho} - 1) - \frac{\hat{\lambda}}{\left( \frac{1}{T^2} \sum_{t=1}^T X_{t-1}^2 \right)} \Rightarrow \frac{\int_0^1 W dW}{\int_0^1 W^2 dr}$$

$$Z_t = \hat{\sigma}_u \hat{W}^{-1} t_\alpha - \hat{\lambda} \left\{ \hat{W} \left( T^{-2} \sum_{t=1}^T X_{t-1}^2 \right)^{1/2} \right\}^{-1} \Rightarrow \frac{\int W dW}{\left( \int W^2 dr \right)^{1/2}}$$

$$\text{where } W(r) = \frac{1}{w} B(r).$$

## EFFICIENT UNIT ROOT TESTS

- When there is no trend/intercept in the model, the DF test is very close to being optimal - i.e. for local alternatives it comes close to having optimal power in relation to the best test computed for the known local alternative using the Neyman-Pearson Lemma (this is the so-called power envelope) and is based on the likelihood ratio

$$\frac{L_{H_0}(\beta=1)}{L_{H_1}(\beta=1+\frac{c}{T}, \text{ given } c)}$$

- However, when there is a trend in the model the DF rely on trend removal by regression and it turns out that efficiency can be gained by "improving" the trend removal process

$$y_t = \beta' D_t + X_t$$

with  $D_t = (1, t, \dots)$  and  $X_t = \rho X_{t-1} + \varepsilon_t$ .  
 Deterministic components

- Under local alternatives  $\rho = 1 + \frac{c}{T}$
- You could use OLS to estimate the deterministic components. This is what DF does
- It makes sense to think that if we find a more efficient method to estimate  $\beta$ , we would get better power
- Elliott, Rothemberg, Stock (1996, Econometrica) proposes to use GLS to estimate  $\beta$  under  $H_1$ , so for different values of " $c$ ".

$$\tilde{\beta} = (\tilde{D}' \tilde{D})^{-1} \tilde{D}' \tilde{y}$$

where

$$\tilde{D}_t = D_t - \rho D_{t-1} = (1 - \rho L) D_t$$

$$\tilde{y}_t = y_t - \rho y_{t-1} = (1 - \rho L) y_t$$

So  $\tilde{y}_t = \tilde{D}_t \beta + X_t$

$$\tilde{X}_t = \tilde{y}_t - \tilde{D}_t \tilde{\beta} = \text{detrended data}$$

Now unit root test on  $\tilde{X}_t$ .

The AD of the DF on the GLS detrending data depends on  $\underline{\epsilon}$ .

For  $D = (1, t)$ , ERS advises to use  $c = 13.5$  and they provide the CVs for that.

## Additional Aspects of Unit Root tests

\* It is commonly claimed that UR tests have serious

- size problems (PP tests)
- power problems (D-F tests)

My opinion is in

"No Lack of Relative Power of the DF Tests"  
J TSA (1996), 17, 37-47 by J. Gonzales and T. Lee

\* Why the null is unit root (non-stationarity) instead of  $|root| < 1$  (stationarity) ?

Think on terms of  
type I - II errors.

To solve the size problems of the PP tests, Perron and Ng (1996)

"Useful Modifications to Some Unit Root Tests with Dependent Errors and Their Local Asymptotic Properties" RES 63, 435-63.

propose some modifications of the PP test.

$$M Z_{\alpha} = Z_{\alpha} + \frac{1}{2} T (\hat{\rho}_T - 1)^2$$

Under  $H_0$   $M Z_{\alpha} \stackrel{d}{=} Z_{\alpha}$

Define  $MSB = \left( T^{-2} \frac{\sum_1^T X_{t-1}^2}{\hat{\omega}^2} \right)^{\frac{1}{2}}$ .

It can be checked that

$$Z_t = MSB \cdot Z_{\alpha}$$

This suggests a new modified PP

$$M Z_t = MSB \cdot M Z_{\alpha}$$

$$M Z_t = Z_t + \frac{1}{2} \left( \frac{\sum_1^T X_{t-1}^2}{\hat{\omega}^2} \right)^{\frac{1}{2}} (\hat{\rho}_T - 1)^2$$

Under  $H_0$   $M Z_t \stackrel{d}{=} Z_t$

Think on how to implement it.

## Testing Stationarity

$H_0$ : no unit root

$H_a$ : unit root

$$y_t = D_t + X_t + v_t$$

$$X_t = X_{t-1} + u_t$$

$$H_0: \sigma_u^2 = 0$$

$$H_a: \sigma_u^2 > 0$$

Let  $\hat{e}_t$  be the residual, from the regression of  $y_t$  on  $D_t$  and  $\hat{\sigma}_v^2 = \frac{1}{T} \sum_{t=1}^T \hat{e}_t^2$ , then the

LM statistic can be constructed as follows

$$LM = \frac{\frac{1}{T^2} \sum_{t=1}^T S_t^2}{\hat{\sigma}_v^2}$$

where  $S_t$  is the partial sum process of the residuals  $\sum_{j=1}^t \hat{e}_j$ .

Under  $H_0$ ,  $\lim_{T \rightarrow \infty} LM \Rightarrow \int_0^1 V(r)^2 dr$ , where  $V(r)$  is a Brownian Bridge ( $B(r) - rB(1)$ )