

1

Consider a market where only one good is traded where the demand at time t is $D_t = 100 - P_t$ and the supply at time y is $S_t = P_{t-2}$, where P_{t-2} and P_t are the prices at times $t - 2$ and t , respectively.

- (a) (5 points) Find a difference equation, linear and of order 2, satisfied by the equilibrium prices. *Note:* The equilibrium prices satisfy $D_t = S_t$ for all t .
 - (b) (5 points) Find the general solution of the difference equation of part (a) above.
 - (c) (5 points) Find the solution of the difference equation of part (a) above which satisfies the initial conditions $P_0 = 40, P_1 = 20$.
 - (d) (5 points) Find the maximum and the minimum equilibrium prices.
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Solution:

(a) $D_t = S_t$ is equivalent to $P_t + P_{t-2} = 100$.

(b) The characteristic equation is $r^2 + 1 = 0$, with solutions $\pm i$. Hence, the general solution of the homogenous equation is $C_1 \cos(\frac{\pi}{2}t) + C_2 \sin(\frac{\pi}{2}t)$. On the other hand, a particular solution of the complete equation is constant, say A , which must satisfy $A + A = 100$, thus $A = 50$. The general solution of the complete equation of part (a) above is thus

$$P_t = C_1 \cos(\frac{\pi}{2}t) + C_2 \sin(\frac{\pi}{2}t) + 50.$$

(c) We have to solve the two equations

$$\begin{aligned} 40 &= C_1 \cos 0 + C_2 \sin 0 + 50 = C_1 + 50, \\ 20 &= C_1 \cos(\frac{\pi}{2}) + C_2 \sin(\frac{\pi}{2}) + 50 = C_2 + 50, \end{aligned}$$

thus $C_1 = -10$ and $C_2 = -30$. Hence the solution satisfying the initial conditions given is

$$P_t = -10 \cos(\frac{\pi}{2}t) - 30 \sin(\frac{\pi}{2}t) + 50.$$

(d) Note that

$$\begin{aligned} \cos(\frac{\pi}{2}t) &= 1, \text{ and } \sin(\frac{\pi}{2}t) = 0, \text{ for all } t = 0, 4, 8, 12, \dots, \\ \cos(\frac{\pi}{2}t) &= 0, \text{ and } \sin(\frac{\pi}{2}t) = 1, \text{ for all } t = 1, 5, 9, 13, \dots, \\ \cos(\frac{\pi}{2}t) &= -1, \text{ and } \sin(\frac{\pi}{2}t) = 0, \text{ for all } t = 2, 6, 10, 14, \dots, \\ \cos(\frac{\pi}{2}t) &= 0, \text{ and } \sin(\frac{\pi}{2}t) = -1, \text{ for all } t = 3, 7, 11, 15, \dots, \end{aligned}$$

Hence

$$\begin{aligned} P_t &= 40, \text{ for all } t = 0, 4, 8, 12, \dots, \\ P_t &= 20, \text{ for all } t = 1, 5, 9, 13, \dots, \\ P_t &= 60, \text{ for all } t = 2, 6, 10, 14, \dots, \\ P_t &= 80, \text{ for all } t = 3, 7, 11, 15, \dots \end{aligned}$$

The solution is a cycle of order 4. The maximum price is 80 and the minimum price is 20.

2

Consider the following linear system of difference equations

$$\begin{pmatrix} x_{t+1} \\ y_{t+1} \\ z_{t+1} \end{pmatrix} = \begin{pmatrix} -1 & 0 & \frac{3}{2} \\ 1 & \frac{1}{2} & -1 \\ -\frac{1}{2} & 0 & 1 \end{pmatrix} \begin{pmatrix} x_t \\ y_t \\ z_t \end{pmatrix} + \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}.$$

- (a) (5 points) Find the equilibrium point and classify it (unstable, stable, locally asymptotically stable or globally asymptotically stable).
- (b) (5 points) Find the general solution of the system.
- (c) (5 points) Find the solution of the system which satisfies the initial conditions $x_0 = 0$, $y_0 = 8$ and $z_0 = 2$.

Solution:

- (a) The equilibrium point is a constant solution of the system, hence it satisfies

$$\begin{aligned} x &= -x + \frac{3}{2}z + 1 \\ y &= x + \frac{1}{2}y - z + 3 \\ z &= -\frac{1}{2}x + z + 1. \end{aligned}$$

The solution is $(x^0, y^0, z^0) = (2, 6, 2)$.

The stability of the equilibrium point depends on the eigenvalues of the system's coefficient matrix

$$A = \begin{pmatrix} -1 & 0 & \frac{3}{2} \\ 1 & \frac{1}{2} & -1 \\ -\frac{1}{2} & 0 & 1 \end{pmatrix}.$$

The characteristic polynomial is $p_A(\lambda) = (\lambda - \frac{1}{2})(-(1+\lambda)(1-\lambda) + \frac{3}{4})$. The second factor is $\lambda^2 - 1 + \frac{3}{4} = \lambda^2 - \frac{1}{4}$. Thus, the eigenvalues of A are $\frac{1}{2}$, double and $-\frac{1}{2}$, simple. Both are smaller than 1 in absolute value, thus the equilibrium point is globally asymptotically stable.

- (b) Let us prove that the matrix A defined above is diagonalizable. We study the rank of the matrix $A - \lambda I_3$ when $\lambda = \frac{1}{2}$. The matrix $A - \frac{1}{2}I_3$ is

$$\begin{pmatrix} -\frac{3}{2} & 0 & \frac{3}{2} \\ 1 & 0 & -1 \\ -\frac{1}{2} & 0 & \frac{1}{2} \end{pmatrix},$$

which rank is 1. Hence, A is diagonalizable. Let us calculate the eigenvectors.

The eigenspace $S(\frac{1}{2})$ is obtained by solving

$$\begin{pmatrix} -\frac{3}{2} & 0 & \frac{3}{2} \\ 1 & 0 & -1 \\ -\frac{1}{2} & 0 & \frac{1}{2} \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

It is clear that $(x, y, z) = x(1, 0, 1) + y(0, 1, 0)$ describe the solutions, thus we take eigenvectors $(1, 0, 1)$ and $(0, 1, 0)$.

The eigenspace $S(-\frac{1}{2})$ is obtained by solving

$$\begin{pmatrix} -\frac{1}{2} & 0 & \frac{3}{2} \\ 1 & 1 & -1 \\ -\frac{1}{2} & 0 & \frac{3}{2} \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

(The matrix above is $A - (-\frac{1}{2})I_3$). We get $x = 3z$ and $y = -2z$, thus the solutions are $(3z, -2z, z) = z(3, -2, 1)$, so we choose the eigenvector $(3, -2, 1)$. In consequence, the general solution of the system is:

$$\begin{pmatrix} x_t \\ y_t \\ z_t \end{pmatrix} = C_1 \left(\frac{1}{2}\right)^t \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + C_2 \left(\frac{1}{2}\right)^t \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + C_3 \left(-\frac{1}{2}\right)^t \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix} + \begin{pmatrix} 2 \\ 6 \\ 2 \end{pmatrix}.$$

- (c) The initial conditions x_0, y_0 y z_0 given in the statement of the exercise determine the value of the constants C_1, C_2 y C_3 . Plugging $t = 0$ into the general solution found above, we get the system

$$\begin{pmatrix} 0 \\ 8 \\ 2 \end{pmatrix} = C_1 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + C_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + C_3 \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix} + \begin{pmatrix} 2 \\ 6 \\ 2 \end{pmatrix}.$$

Solving, $C_1 = 1$, $C_2 = 0$ and $C_3 = -1$. The requested solution is thus:

$$\begin{pmatrix} x_t \\ y_t \\ z_t \end{pmatrix} = \left(\frac{1}{2}\right)^t \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - \left(-\frac{1}{2}\right)^t \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix} + \begin{pmatrix} 2 \\ 6 \\ 2 \end{pmatrix}, \quad t = 0, 1, 2, \dots$$

3

Answer the following questions.

- (a) (5 points) Find the general solution of the ODE

$$(1+t)x' + x = t(t+1).$$

- (b) (5 points) Find the solution of the ODE

$$(1+t)x' + x = t(t+1)$$

which satisfies $x(0) = x(1)$.

Solution:

The ODE is written in the usual form

$$x' + \frac{x}{1+t} = t,$$

for $t \neq -1$.

- (a) One of the methods to integrate linear ODEs consists in calculating

$$\mu(t) = e^{\int \frac{1}{t+1} dt} = t+1$$

and then, after multiplying the ODE by $\mu(t)$, to obtain

$$\left(x' + \frac{x}{t+1}\right)(t+1) = t(t+1) \Rightarrow (x(t+1))' = t(t+1) \Rightarrow x(t+1) = \int t(t+1) dt.$$

After integrating and solving for $x(t)$ we obtain the general solution

$$x(t) = \frac{C}{t+1} + \frac{t^3}{3} + \frac{t^2}{2}.$$

- (b) Imposing $x(0) = x(1)$ with the expression found for the general solution in part (a), we have

$$\frac{C}{t+1} + \frac{t^3}{3} + \frac{t^2}{2} \Big|_{t=0} = \frac{C}{t+1} + \frac{t^3}{3} + \frac{t^2}{2} \Big|_{t=1},$$

that is, $C = \frac{C}{2} + \frac{1}{6} + \frac{1}{4}$, thus $C = \frac{5}{6}$. The solution in question is

$$x(t) = \frac{5}{6(t+1)} + \frac{t^3}{3} + \frac{t^2}{2}.$$

4

Find the general solution of the ODE

$$x'' - x' = e^{at},$$

where $a \in \mathbb{R}$, in each of the following cases:

- (a) (5 points) When $a = 0$.
- (b) (5 points) When $a = 1$.
- (c) (5 points) When $a \neq 0$ and $a \neq 1$.

Solution:

The homogenous ODE has general solution $C_1 + C_2e^t$.

- (a) When $a = 0$, the ODE is $x'' - x' = 1$. Since constants are solution of the homogenous ODE, a particular solution of the complete ODE is $x_p(t) = At$ with suitable A . The coefficient A is found from $1 = x_p'' - x_p' = -A$, thus $A = -1$. In consequence, the general solution of the complete ODE is given by

$$C_1 + C_2e^t - t.$$

- (b) When $a = 1$, the ODE is $x'' - x' = e^t$. Since e^t is a solution of the homogenous ODE, a particular solution of the complete ODE is $x_p(t) = Ate^t$ with a suitable A . We calculate

$$\begin{aligned} x_p' &= A(t+1)e^t \\ x_p'' &= A(t+2)e^t. \end{aligned}$$

The coefficient A is found from

$$e^t = x_p'' - x_p' = A(t+2)e^t - A(t+1)e^t,$$

which holds for all t iff $A = 1$. In consequence, the general solution of the complete ODE is given by

$$C_1 + C_2e^t + te^t.$$

- (c) When a is not 0 nor 1, the ODE is $x'' - x' = e^{at}$, where e^{at} is not solution of the homogenous ODE. A particular solution of the complete ODE is $x_p(t) = Ae^{at}$ with suitable A . We calculate

$$\begin{aligned} x_p' &= aAe^{at} \\ x_p'' &= a^2Ae^{at}. \end{aligned}$$

The coefficient A is found from

$$e^{at} = x_p'' - x_p' = a^2Ae^{at} - aAe^{at},$$

from which $A = 1/(a^2 - a)$. In consequence, the general solution of the complete ODE is given by

$$C_1 + C_2e^t + \frac{1}{a^2 - a}e^{at}.$$

5

Consider the following system of differential equations

$$\begin{cases} x' = -2x - y \\ y' = x - 2y \end{cases}$$

Find and classify the equilibrium point. Sketch the phase diagram.

Solution:

The equilibrium point is $(0, 0)$. The characteristic polynomial of the system matrix, $A = \begin{pmatrix} -2 & -1 \\ 1 & -2 \end{pmatrix}$, is $p_A(\lambda) = (2 + \lambda)^2 + 1$, which roots are found from $2 + \lambda = \pm\sqrt{-1} = \pm i$. Thus, the roots are complex, $-2 + i$ and $-2 - i$, both with negative real part. Hence the equilibrium point is globally asymptotically stable and it is an attractive spiral.

