# Chapter 5 Static Games with asymmetric information

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### 1 The Bayesian equilibrium

**Definition 1.1.** A Bayesian game G consists of the following,

$$G = (N, A, T, \{p_i\}_{i=1}^n, \{u_i\}_{i=1}^n)$$

where we have

- The set of *players*  $N = \{1, 2, ..., n\}.$
- The space of actions  $A_1, A_2, \ldots, A_n$  of each player.  $A = A_1 \times A_2 \times \cdots \times A_n, a = (a_1, a_2, \ldots, a_n)$
- The set of possible types  $T_1, T_2, \ldots, T_n$  for each player. The type  $t_i \in T_i$  is known only by player  $i = 1, 2, \ldots, n$ .
- The set of all the types is  $T = T_1 \times T_2 \times \cdots \times T_n$ . We use the notation  $t = (t_1, t_2, \ldots, t_n), t_{-i} = (t_1, t_2, \ldots, t_{i-1}, t_{i+1}, \ldots, t_n).$
- Each player *i* has a conjecure  $p_i: T_i \to \Delta(T_{-i})$  about the types of the other players. It may depend on its own type

$$p_i = p_i(t_{-i}|t_i)$$

and it is interpreted as the information that agent i has on the types of the other agents  $(t_{-i})$ , given that his type is  $t_i$ .

• The conjectures of the agents have to be consistent and compatible with Bayes rule: There is a distribution of probabilities  $q \in \Delta(T)$  such that

$$p_i(t_{-i}|t_i) = \frac{q(t_1...,t_n)}{\sum_{s_{-i}\in T_{-i}} q(t_i,s_{-i})}$$

We interpret  $q(t_1, \ldots, t_n)$  as the probability that agent 1 is of type  $t_1$ , agent 2 is of type  $t_2, \ldots$  and agent n is of type  $t_n$ . The denominator  $\sum_{s_{-i} \in T_{-i}} q(t_i, s_{-i})$  is the probability that the agent of type i be  $t_i$ . That is,  $p_i(t_{-i}|t_i)$  is, according to Bayes rule, the probability that the other agents have the type  $t_{-i}$ , given that the type of agent i is  $t_i$ .

• A **pure strategy** of player *i*,

$$s_i: T_i \to A_i$$

specifies the action of each of player for each of his possible types i.

• A mixed strategy of player *i*,

$$\sigma_i: T_i \to \Delta(A_i)$$

is a vector  $\sigma_i(t_i) = (\sigma_i(a_1, t_i), \dots, \sigma_i(a_n, t_i))$ . Here,  $\sigma_i(a_k, t_i)$  is the probability that agent *i* of type  $t_i$  plays the strategy  $a_k$ .

• The functions of utility over outcomes: of the agents  $u_1, u_2, \ldots, u_n$  are of the form

$$u_i: A \times T \to \mathbb{R}$$

 $u_i(a;t)$  depends on the types  $t = (t_1, \ldots, t_n)$  and on the actions of all the agents  $a = (a_1, \ldots, a_n)$ .

• Utility functions over strategies: The expected utility of agent i when he plays strategy  $a_i$ , given that the other agents are playing the pure strategies  $s_k$  is

$$U_i(s_1, \dots, s_{t_i-1}, a_i, s_{t_i+1}, \dots, s_n) =$$

$$\sum_{a_i \in T_{-i}} u_i(s_1(t_1), \dots, s_{t_{i-1}}(t_{i-1}), a_i, s_{t_{i+1}}(t_{i+1}), \dots, s_n(t_n); t) p_i(t_{-i}|t_i)$$

• The notion of equilibrium is the NE with the above expected utility functions.

## 2 Cournot competition with asymmetric information

#### **Cournot Duopoly**

- Suppose there are two companies which compete in quantities (Cournot's competion).
- The inverse demand is

where

 $q = q_1 + q_2$ 

P(q) = a - q

and  $q_1, q_2$  are the amounts produced by the companies.

• The cost function of Firm 1 is

t

$$c_1(q_1) = cq_1$$

• The cost function of Firm 2 is

$$c_2(q_2) = \begin{cases} c_a q_2 & \text{with probability } \theta \\ c_b q_2 & \text{with probability } 1 - \theta \end{cases}$$

with  $c_b < c_a$ .

- There is asymmetric information:
  - Firm 2 knows its cost cost function  $(c_a \text{ or } c_b)$  and knows the cost of Firm 1.
  - But, Firm 1 only knows its cost function. It also knows that the marginal cost of Firm 2 is  $c_a$  with probability  $\theta$  and  $c_b$  with probability  $1 \theta$ .
  - Firm 2 has more information than Firm 1.
- First we represent this situation as a **Bayesian Game**.
- The players are  $N = \{1, 2\}$ .
- The types are the cost functions of the companies  $T_1 = \{c\}$   $T_2 = \{c_a, c_b\}$ .
- The utility functions are the profits,

$$\begin{aligned} \pi_1(q_1, q_2, c) &= (a - q_1 - q_2)q_1 - cq_1 = (a - q_1 - q_2 - c)q_1 \\ \pi_2(q_1, q_a, c_a) &= (a - q_1 - q_a)q_a - c_aq_a = (a - q_1 - q_2 - c_a)q_a \\ \pi_2(q_1, q_b, c_b) &= (a - q_1 - q_b)q_b - c_bq_b = (a - q_1 - q_2 - c_b)q_b \end{aligned}$$

- The sets of actions are  $A_c = A_a = A_b = [0, \infty)$ .
- The conjectures of the firms are

$$p_2(t_1 = c|c_a) = p_2(t_1 = c|c_b) = 1$$

and

$$p_1(t_2 = c_a|c) = \theta, \quad p_1(t_2 = c_b|c) = 1 - \theta$$

#### Best response of Firm 2

• If the cost function of Firm 2 is  $c_a$  then it solves the following problem

$$\max_{q_a} (a - q_1 - q_a) q_a - c_a q_a = \max_{q_2} (a - q_1 - q_a - c_a) q_a$$

• The FOC's are  $a - q_1 - 2q_a - c_a = 0$  so the best response for Firm 2 provided its cost is  $c_a$  and that Firm 1 produces  $q_1$  is

$$q_a = q_2(c_a) = \frac{a - q_1 - c_a}{2}$$

• If the cost function of Firm 2 is  $c_b$  then it solves the following problem

$$q_b = \max_{q_2} (a - q_1 - q_b) q_b - c_b q_b = \max_{q_2} (a - q_1 - q_b - c_b) q_b$$

• The FOC's for the firm are  $a - q_1 - 2q_b - c_b = 0$  so the best response for Firm 2 if its cost is  $c_b$  and firm 1 produces  $q_1$  is

$$q_b = q_2(c_b) = \frac{a - q_1 - c_b}{2}$$

#### Best response of Firm 1

• Firm 1 does not know the cost function of Firm 2. It maximizes expected profit (EP)

$$\max_{q_1} \quad \theta \underbrace{(a-q_1-q_2(c_a)-c) q_1}_{\text{EP if firm 2's cost is } c_a} + (1-\theta) \underbrace{(a-q_1-q_2(c_b)-c) q_1}_{\text{EP if firm 2's cost is } c_b}$$

• The FOC is

$$\theta (a - 2q_1 - q_2(c_a) - c) + (1 - \theta) (a - 2q_1 - q_2(c_b) - c) = 0$$

• We obtain the reaction function of Firm 1

$$q_1 = \frac{\theta \left(a - q_2(c_a) - c\right) + (1 - \theta) \left(a - q_2(c_b) - c\right)}{2}$$

• The NE satisfies the equations

$$q_{1} = \frac{\theta \left(a - q_{2}(c_{a}) - c\right) + (1 - \theta) \left(a - q_{2}(c_{b}) - c\right)}{2}$$

$$q_{2}(c_{a}) = \frac{a - q_{1} - c_{a}}{2}$$

$$q_{2}(c_{b}) = \frac{a - q_{1} - c_{b}}{2}$$

Solving for  $q_2(c_a)$  and  $q_2(c_b)$  in the first equation, we obtain

$$2q_1 = \theta \left( a - \frac{a - q_1 - c_a}{2} - c \right) + (1 - \theta) \left( a - \frac{a - q_1 - c_b}{2} - c \right)$$

• and from here we see that

$$q_1 = \frac{a - 2c + \theta c_a + (1 - \theta)c_b}{3}$$

• Substituting this value we obtain that

$$q_1^* = \frac{a - 2c + \theta c_a + (1 - \theta)c_b}{3}$$
$$q_2^*(c_a) = \frac{a - 2c_a + c}{3} + \frac{1 - \theta}{6}(c_a - c_b)$$
$$q_2^*(c_b) = \frac{a - 2c_b + c}{3} - \frac{\theta}{6}(c_a - c_b)$$

#### Comparison with the Cournot equilibrium with complete information

• With complete information and cost functions  $c_1$ ,  $c_2$  Cournot's equilibrium is

$$\bar{q}_1 = \frac{a - 2c_1 + c_2}{3}$$
  $\bar{q}_2 = \frac{a - 2c_2 + c_1}{3}$ 

- We observe that the case with complete information can be obtained from the incomplete information case by setting  $c_2 = c_a = c_b$ .
- Let us call

$$\bar{q}_1(c_a) = \frac{a - 2c_1 + c_a}{3}$$

the production of Firm 1 if it knows that the cost function of Firm 2 is  $c_a$ .

• and

$$\bar{q}_1(c_b) = rac{a - 2c_1 + c_b}{3}$$

the production of Firm 1 if it knows that the cost function of Firm 2 es  $c_b$ .

• Then,

$$\bar{q}_1(c_a) \ge q_1^* \ge \bar{q}_1(c_b)$$

• Note that

$$q_2^*(c_a) > \frac{a - 2c_a + c_1}{3}$$
  
 $q_2^*(c_b) < \frac{a - 2c_b + c_1}{3}$ 

• This happens because Firm 2 adjusts its production not only to its own cost, but it also takes into account that Firm 1 doesn't know the cost function of Firm 2 and adopts a production in between those that would adopt if it knew that the cost of Firm 2 is either a or b.

## 3 Sealed bid auctions

- Two agents, i = 1, 2, participate in an auction. The agents bid simultaneously. The highest bidder wins: gets the object and pays his bid. In case of a tie, the winner is determined by a fair lottery.
- Private value auctions: Each bidder *i* knows only his valuation of the object,  $v_i \in [0, 1]$ , but the valuation  $v_j$  of the other bidder. He only knows the distribution function of  $v_j$ . Let us assume that the valuations of the bidders are independent and uniformly distributed on the interval [0, 1]. That is,

$$\operatorname{prob}(v_j \le x) = x$$

- Agents are risk neutral: If his valuation is v, wins the object and pays p, his payoff is v p.
- We write this mechanism as a Baysian Game and find the equilibria.
  - 1. The types of the agents are  $T_1 = T_2 = [0, 1]$ .
  - 2. The probability of each type is described by  $\operatorname{prob}(v_j \leq x) = x$ . Theses are the conjectures of the agents.
  - 3. The sets of actions are  $A_1 = A_2 = [0, 1]$ . We denote de action of agent i = 1, 2 by  $b_i \in A_i$ .

#### Utility functions

- The utility function of agent i = 1, 2, given that
  - his valuation is  $v_i$ ,
  - he bids  $b_i$ , and
  - the other agent bids  $b_i$

is

$$u_i(b_i, b_j | v_i) = \begin{cases} v_i - b_i, & \text{if } b_i > b_j; \\ 0, & \text{if } b_i < b_j; \\ (v_i - b_i)/2 & \text{if } b_i = b_j. \end{cases}$$

- A strategy for agent *i* is a function  $b_i(v_i)$  from  $T_i$  into  $A_i$ .
- Given that j = 1, 2 uses the strategy  $b_j(v_j)$ , the best reply of agent *i* is the solution of the following maximization problem

$$\max_{b_i} (v_i - b_i) \operatorname{prob}(b_i > b_j(v_j)) + \frac{1}{2}(v_i - b_i) \operatorname{prob}(b_i = b_j(v_j))$$

Since,  $\operatorname{prob}(b_i = b_j(v_j)) = 0$  the above problem is equivalent to the following one

$$\max_{b_i} (v_i - b_i) \operatorname{prob}(b_i > b_j(v_j))$$

• Ww show now that there is an equilibrium that is symmetric and linear. That is,

$$b_i(v) = b_j(v) = Av$$

- and we have to determine the value of A.
- The maximization problem becomes

$$\max_{b_i} (v_i - b_i) \operatorname{prob}(b_i > b_j(v_j)) = \max_{b_i} (v_i - b_i) \operatorname{prob}(b_i > Av_j) =$$
$$= \max_{b_i} (v_i - b_i) \operatorname{prob}\left(v_j < \frac{b_i}{A}\right) = \max_{b_i} (v_i - b_i) \frac{b_i}{A}$$

• The FOC is

$$v_i - 2b_i = 0$$

• And we see that

 $b_i = \frac{v_i}{2}$ 

is a symmetric BE.

## 4 Public Goods

- Two neighbors live in an island with no highways. The government plans to build one at the cost of 20 million. The **monetary value** of the road for a user is the following.
  - 30 million if the user has a car
  - 0, if the user does not have a car.
- the probability that a neighbor owns a car is

 $p(\operatorname{car}) = p$ 

- This information is public and known by the agents.
- To take a decision wether to build the road or not to build the road the government considers the two following possible procedures.

#### 4.1 Mechanism A

#### Mechanism A

- Each neighbor fills up a questionnaire stating wether he has a car or not.
- It is understood that a neighbor that claims to have a car is willing to contribute up to 30 million towards the construction of the road.
- If the number of neighbors that claim to have a car is enough to cover the cost of the road, then the road tis build and the cost it is divided evenly among all those neighbors.
- If the number of neighbors that claim to have a car is NOT enough to cover the cost of the road, then the road is build.
- Let us describe this mechanism as a Bayesian game and compute the equilibria.
- The types of agents are  $T_1 = T_2 = \{\text{car, no car}\}$ . But it will be more convenient to use the value that the each type of user assigns to building the road  $T_1 = T_2 = \{0, 30\}$ .
- The probability of each type is p(0) = 1 p, p(30) = p. These are the conjectures of the agents

$$p_i(t_j = 30|t_i) = p$$

- The set of actions of the agents is  $A_1 = A_2 = \{yes, no\}.$
- Let us denote the action of agent i = 1, 2 by  $a_i$ . The strategy of agent i = 1, 2 is a function  $T \to A_i$ .

#### Utility functions

• The utility function of agent i = 1, 2 is (it is understood that  $i \neq j$ )

$$u_i(a_1, a_2 | t_i) = \begin{cases} t_i - 20, & \text{if } a_i = \text{yes y } a_j = \text{no;} \\ t_i, & \text{if } a_i = \text{no y } a_j = \text{yes;} \\ t_i - 10, & \text{if } a_i = a_j = \text{yes;} \\ 0, & \text{if } a_i = a_j = \text{no.} \end{cases}$$

• Note that

$$u_i(a_1, a_2 | t_i = 0) = \begin{cases} -20, & \text{if } a_i = \text{yes y } a_j = \text{no;} \\ 0, & \text{if } a_i = \text{no y } a_j = \text{yes;} \\ -10, & \text{if } a_i = a_j = \text{yes;} \\ 0, & \text{if } a_i = a_j = \text{no.} \end{cases}$$

That is, the action

$$a_i(0) = \mathrm{no}$$

is a dominant strategy.

#### **Complete information**

• Suppose that  $t_1 = 30 \text{ y } t_2 = 0$ . The game is

	yes	no
yes	20, -10	10, 0
no	30, -20	0,0

The unique NE is (yes, no).

• Suppose that  $t_1 = t_2 = 30$ . The game is

	yes	no	
yes	20, 20	10, 30	
no	30, 10	0,0	

- There are three NE
  - (yes, no), (no, yes) and
  - a NE in mixed strategies

$$\left(\frac{1}{2}\text{yes} + \frac{1}{2}\text{no}, \frac{1}{2}\text{yes} + \frac{1}{2}\text{no}\right)$$

#### **Incomplete** information

- Let us search for a symmetric equilibrium in pure strategies.
- Symmetric equilibrium means that  $a_1(t) = a_2(t)$  for every  $t \in T$ .
- In equilibrium,  $a_1(0) = a_2(0) =$ no.
- Is  $a_1(30) = a_2(30) = \text{yes}$  an equilibrium?
- Suppose that  $t_i = 30$ . (the agent *i* has a car)
- The expected payoff of this agent with the above strategy is

$$pu_i(\text{yes}, a_j(30)|30) + (1-p)u_i(\text{yes}, a_j(0)|30) =$$
  

$$pu_i(\text{yes}, \text{yes}|30) + (1-p)u_i(\text{yes}, \text{no}|30) =$$
  

$$p(30-10) + (1-p)(30-20) = 10p + 10$$

#### Symmetric equilibrium in pure strategies

• On the other hand, if he deviates and follows the strategy  $b_i = no$ , his expected payoff is

$$pu_i(no, a_i(30)|30) + (1-p)u_i(no, a_i(0)|30) = pu_i(no, yes|30) + (1-p)u_i(no, no|30) = p(30-0) + (1-p) \times 0 = 30p$$

• Therefore, the strategy

$$a_1(30) = a_2(30) =$$
yes

is a BE if  $10 + 10p \ge 30p$ , that is if  $p \le 1/2$ .

• Summary: if  $p \leq 1/2$  there is a symmetric BE in pure strategies

$$a_1(0) = a_2(0) = no$$
  
 $a_1(30) = a_2(30) = yes$ 

• This equilibrium is efficient: The road is build whenever  $t_1 + t_2 > 20$ .

#### Is there any other symmetric equilibrium in pure strategies?

- Is  $a_i(30) = a_i(0) = \text{no } i = 1, 2 \text{ a BE}?$
- The expected payoff with this strategy is 0.
- Whereas if an agent deviates, his expected payoff is 10.
- Therefore,  $a_i(30) = a_i(0) = \text{no } i = 1, 2 \text{ is not a BE.}$

#### Incomplete information. Symmetric equilibrium in mixed strategies

- Now we ask if there exists a symmetric BE in **mixed strategies** when p > 1/2.
- The symmetric equilibrium in mixed strategies must be of the form

$$a_1(30) = a_2(30) = w$$
 yes  $+ (1 - w)$  no =

- Suppose that the agent *i* is of type  $t_i = 30$ . Recall that a necessary condition for the above strategy to be NE in mixed strategies is that the agent be indifferent among  $a_i(30) = \text{yes}$  and  $a_i(30) = \text{no}$ . Let us express this condition.
- When the agent declares  $a_i(30) = \text{yes}$  and the other agent  $j \neq i$  follows the mixed strategy  $a_j(30) = (w, 1 w)$  then the expected payoff for agent i is

$$p \Big[ w \, u_i(\text{yes}, \text{yes}|30) + (1-w) \, u_i(\text{yes}, \text{no}|30) \Big] \\ + (1-p) u_i(\text{yes}, \text{no}|30) = \\ p \Big[ w(30-10) + (1-w)(30-20) \Big] + (1-p)(30-20) = \\ = 10 + 10pw$$

• If the agent declares  $a_i(30) = no$  and the other agent  $j \neq i$  follows the mixed strategy  $a_j(30) = (w, 1 - w)$  then the expected payoff for agent *i* is

$$p \Big[ w \, u_i(\text{no}, \text{yes}|30) + (1-w) \, u_i(\text{no}, \text{no}|30) \Big] \\ + (1-p) u_i(\text{no}, \text{no}|30) = \\ p \Big[ w \cdot 30 + (1-w) \cdot 0 \Big] + (1-p) \cdot 0 = \\ = 30pw$$

• Therefore, the strategy  $a_1(30) = a_2(30) = w \operatorname{yes} + (1 - w) \operatorname{no}$  is a BE if

$$10 + 10pw = 30pw$$

that is, if

$$w = \frac{1}{2p} \qquad \frac{1}{2} \le p \le 1$$

• Hence, we have found that

1. If  $p \leq 1/2$  then

$$a_i(0) = no, \quad a_i(30) = yes$$

is a BE.

2. If p > 1/2 then

$$a_i(0) = no, \quad a_i(30) = \frac{1}{2p} \operatorname{yes} + (1 - \frac{1}{2p}) \operatorname{no}$$

is a BE.

#### Efficiency

- What is the probability that it is efficient to build the road?
- There are four possible cases,

	(30, 30)	(30, 0)	(0, 30)	(0, 0)
Efficient	yes	yes	yes	no
prob	$p^2$	p(1-p)	p(1-p)	$(1-p)^2$

• The probability that building the road is efficient is

$$p^2 + 2p(1-p) = 2p - p^2$$

- What is the probability that the road is built if mechanism A is adopted?
- if  $p \le 1/2$ ,

	(30, 30)	(30, 0)	(0, 30)	(0, 0)
prob	$p^2$	p(1-p)	p(1-p)	$(1-p)^2$
prob. of building	1	1	1	0

• The probability of building the road is

$$p^{2} + 2p(1-p) = 2p - p^{2} \le \frac{1}{2}$$

• The probability of building the road coincides with the probability that it is efficient to build it.

• But, if p > 1/2,

	(30, 30)	(30, 0)	(0, 30)	(0, 0)
prob	$p^2$	p(1-p)	p(1-p)	$(1-p)^2$
prob.	$1 - (1 - w)^2$	w	w	0
of building	$= 2w - w^2$			

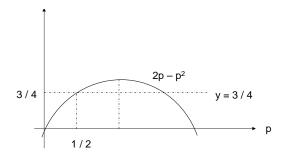
• The probability of building the road is

$$p^{2}(2w - w^{2}) + 2p(1 - p)w = \frac{3}{4}$$

• The mechanism is inefficient with probability

$$p^{2}(1-w)^{2} + 2p(1-p)(1-w) = 2p - p^{2} - \frac{3}{4}$$

• The graph of the function  $2p - p^2$  is



• We see that if 1/2 , then

$$2p - p^2 > \frac{3}{4}$$

• The probability of building the road is lower than the probability that it is efficient to build it.

#### 4.2 Mechanism B

#### Mechanism B

- We order the agents i = 1, 2. agent 1 indicates how much he is willing to pay in order to build the road:  $\xi_1 \in [0, 20]$ .
- Agent 2 knowing  $\xi_1$  informs of his decision
  - 1. 'yes': then the road is build and agents pay the amounts  $\xi_1$  and  $\xi_2 = 20 \xi_1$ .
  - 2. 'no': then the road is not build and agents pay the amounts  $\xi_1 = 0$  and  $\xi_2 = 0$ .
- Let us write this mechanism as Bayesian game and compute the equilibria.
- the types of the agents are  $T = T_1 = T_2 = \{\text{car, no car}\}$ . As a type we continue to use the value that each assigns to building the road  $T = T_1 = T_2 = \{0, 30\}$ .
- the probability of each type is p(0) = 1 p, p(30) = p. These are the conjectures of the agents  $p_i(t_i = 30) = p$
- the sets of actions of the agents are  $A_1 = [0, 20], A_2 = \{yes, no\}.$
- We denote the action of agent i = 1, 2 by  $a_i$ . The strategy of agent 1 is a function  $a_1 : T_1 \to A_1$ . The strategy of agent 2 is a function  $a_2 : T_2 \times A_1 \to A_2$ .

#### Utility functions

• the utility function of agent 1 is

$$u_1(a_1, a_2, t_1) = \begin{cases} t_1 - a_1, & \text{if } a_2 = \text{yes}; \\ 0, & \text{if } a_2 = \text{no.} \end{cases}$$

• the utility function of agent 2 is

$$u_2(a_1, a_2|t_1) = \begin{cases} t_2 - (20 - a_1), & \text{if } a_2 = \text{yes}; \\ 0, & \text{if } a_2 = \text{no.} \end{cases}$$

#### Second stage

- Let us compute the BE. Since, it is a sequential game, we solve it by backwards induction. First, we analyze the actions of *player 2*.
- if player 1 chooses the action  $a_1$ , the payoffs of player 2 are
  - 1.  $u_2 = t_2 (20 a_1) = t_2 20 + a_1$ , when  $a_2 =$  yes. 2.  $u_2 = 0$ , when  $a_2 =$  no.
- the best reply of player 1 is

$$a_2(30, a_1) = \text{yes}, \qquad a_2(0, a_1) = \begin{cases} \text{no} & \text{if } a_1 < 20; \\ \text{yes}, & \text{if } a_1 = 20. \end{cases}$$

#### First stage

- player 1 anticipates the reaction of player 2.
- if the type of player 1 is  $t_1 = 0$ , his best strategy is to choose  $a_1(0) = 0$ .
- Suppose now that the type of player 2 is  $t_1 = 30$  and let us find his optimal strategy.
- if his message is  $a_1 = 20$ , then his expected utility is 10.
- if his message is  $a_1 < 20$ , then his expected utility is

$$p(30 - a_1) + (1 - p) \cdot 0 = 30p - pa_1$$

- that is, among all the messages  $a_1 < 20$  his optimal strategy is to choose  $a_1 = 0$ . And his expected utility is 30p.
- Player 1 decides wether his message is  $a_1 = 20$  or  $a_1 = 0$ .
- he chooses  $a_1 = 0$  if 30p > 10. or if

$$p > \frac{1}{3}$$

• Hence,

$$a_1(0) = 0 \qquad a_1(30) = \begin{cases} 0, & \text{if } p > 1/3; \\ 20, & \text{if } p < 1/3; \\ [0, 20], & \text{if } p = 1/3. \end{cases}$$

#### Equilibrium

• In brief, the BE is

$$a_1(0) = 0 \qquad a_1(30) = \begin{cases} 0, & \text{if } p > 1/3; \\ 20, & \text{if } p < 1/3; \\ [0,20], & \text{if } p = 1/3. \end{cases}$$
$$a_2(30,a_1) = \text{yes}, \qquad a_2(0,a_1) = \begin{cases} \text{no} & \text{if } a_1 < 20; \\ \text{yes}, & \text{if } a_1 = 20. \end{cases}$$

#### Efficiency

• What is the probability that the road is build if mechanism B is the one adopted?

	(30, 30)	(30, 0)	(0, 30)	(0, 0)
Efficient	yes	yes	yes	no
prob	$p^2$	p(1-p)	p(1-p)	$(1-p)^2$
road is	yes	yes when $p < 1/3$	yes	no
build		no when $p > 1/3$		

- The probability that building the road is efficient is  $p^2 + 2p(1-p) = 2p p^2$ .
- The probability of building the road is

$$p^{2} + 2p(1-p) = 2p - p^{2}$$
 if  $p < 1/3$   
 $p^{2} + p(1-p) = p$  if  $p > 1/3$ 

- If p > 1/3, the mechanism is inefficient with probability  $p(1-p) = p p^2$ .
- Which of the two mechanisms is more efficient?
- Mechanism A is more inefficient than B if

$$2p - p^2 - \frac{3}{4} > p - p^2$$

that is, if

$$p>\frac{3}{4}$$

## 5 More information could be worse

• Consider the following game with incomplete information,

	L	М	R		L	М	R	
Т	1,1/2	1,0	1,3/4	т	1,1/2	1,3/4	1,0	
В	2,2	0,0	0,3	В	2,2	0,3	0,0	
1	2	w <sub>1</sub>	1/2		W <sub>2</sub>	1/2		

- The agents believe that with probability 1/2 they play the game  $w_1$  and with probability 1/2 they play the game  $w_2$ .
- The unique NE is (B, L). Each player gets an expected payoff of 2.
- Suppose now that player 2 knows if the true game played is  $w_1$  or  $w_2$ . In this case, the unique NE is (T, R) ó (T, M). The payoff of player 2 is 3/4. He would have preferred not to be informed.
- But, can player 2 credibly commit to ignore the information he has received?